TECNOTION®

direct drive in motion

IRON CORE LINEAR MOTOR SERIES

Extremely high force

WE DIRECT DRIVE YOUR MOTION TECHNOLOGY

Direct drive motors from Tecnotion are seamlessly integrated into a wide range of applications, including semiconductors, machine tooling, robotics, display applications and printing. As an independent supplier of linear, torque and vacuum motors, we offer specialized motor technology to place in your motion solutions.

We have distinguished ourselves for almost 30 years with the exclusive development and production of direct drive linear and torque motors. As a result, we succeed in providing the best motor solution for your motion needs, whether it is a catalogue or a custom motor. Thanks to our extensive experience we are used to designing and building any motion requirement with unmatched quality & performance.

Support

At Tecnotion, we recognize that every use of our motors presents unique circumstances with different needs and challenges. Our team of Sales and Application Engineers have extensive experience in different application scenarios and work closely with our customers to find solutions that perfectly align with their requirements and objectives.

With our commitment to excellence and innovation, we remain steadfast in our mission to provide our customers with solutions that lead them to success in an ever-changing landscape.

Continuous innovation

At the heart of our company is an internal Research and Development (R&D) department that serves as an engine for innovation. This dedication to innovation not only fuels our deep knowledge of manufacturing processes, but also drives our commitment to excel in product design and performance, helping our customers meet the changing needs and expectations of their customers.

In addition to our extensive range of off-the-shelf standard motors, we custom design motors for applications that have more unique requirements. Our team works closely with customers to understand their specific challenges and objectives.

Modern manufacturing

Our manufacturing capabilities are strategically distributed between our facilities in China, Vietnam and the Netherlands, each of which plays a vital role in delivering first-class products to our customers worldwide. This distribution enables us to meet the demands of mass production.

Our competence centre and headquarters in the Netherlands are dedicated to advanced motor technology and are the epicentre of innovation and precision engineering. Custom motors are also built here in our special state-of-the-art clean room environment, with extreme precision and an eye for quality. Tecnotion prides itself on maintaining the strictest quality standards in all facets of our operations. Our plants are ISO 9001 certified.

Global logistics

We ensure that our most popular products are in stock in our warehouses. This setup gives us quick access to our stock, regardless of your location. Whether you are near our European headquarters or on the other side of the world, our efficient shipping network ensures that your orders are processed quickly.

Even during periods of increased market activity, our flexible supply chain allows us to maintain fast delivery times, so your products reach you quickly and reliably. With our unwavering commitment to customer satisfaction and operational excellence, we strive to provide seamless and efficient service throughout the supply chain.

Iron core motor series

T	L M	X	6 12	S N

T = Iron core
L M = Series type
X = Magnet plate type
6 12 = Number of coils
S N = Winding type

TBW series

F_u 2700-6750 N F_{cw} 1200-3000 N

The TBW series is the water cooled variant of the TB series. It features a fully integrated, highly efficient cooling system which enables the TBW to reach even higher continuous forces than the standard version and sustain extreme accelerations while maintaining its sub-micron position accuracy.
Since heat is not dissipated into the machine's construction, it is especially suited for applications where thermal management is an issue.

TB series

F_u 1800-4500 N F_c 760-1900 N

The high-end TB motors are heavy duty workhorses that combine high acceleration and speed, sub-micron positioning accuracy and low power consumption with a superb force density. They excel in applications where high loads and long duty cycles are the order of the day. When you require a motor that takes your application to new levels, the TB more than delivers.

TL series

F_u 450-3600 N F_{cw} 210-1680 N

The mid-range TL is our most popular iron core motor. It features an extremely low attraction force between the coils and the magnets and stands out for its small size, high acceleration, high speed and accuracy. The TL is also available in long versions, which makes this all-rounder suited for nearly any application, including those with long travel lengths, like printers for large digital formats.

TM series

F_u 120-720 N F_c 60-360 N

For applications that do not require high forces, it is often more effective to use a smaller and less costly motor. Over the years, the TM series has proven to be a very versatile, reliable and efficient motor for a wide range of applications. To enhance its effectiveness, the TM linear motor is equipped with a long flexible servo cable which makes the use of additional connectors superfluous and reduces total cost of ownership even further.

New

TD55 series

F_u 211-422 N F_c 106-213 N

Unique low build height

This motor has a low height which makes it perfect for every application where space is limited without compromising on continuous force.

The small package adds the benefit of a very light coil unit

New

TD82 series

F_u 453-905 N F_c 256-524 N

Ultra short build size

The surpising force density of the TD82 provides you all the continuous force you need for your application.

This force in a small package gives you the largest available stroke length.

New

TxX series

Higher force density

The TxX series can significantly enhance the performance of your system. The new TxX iron core linear motors have an optimized force constant, making your system more efficient and capable of handling heavier loads or higher accelerations.
The use of stronger magnet plates in the TxX series can allow for smaller motor size design reducing the space required in your system.
Using stronger magnetic plates in the TxX series allows for a smaller motor that takes up less space in your system.

Parameter	TM & TL	TB & TBW
F_u, F_p, F_c (N)	+18%	+15%
S (N^2/W)	+39%	+32%

Features

Iron core linear motor series

F/cm³

High force density

More force in a small design means lowering footprint and it fits better in tight spaces.

Aluminum housed design

Enclosed design in aluminum, with integrated water cooling for TBW- and TL series.

Low cogging

Optimized iron core motor design, for smooth motion and position and accuracy in your application.

Coil

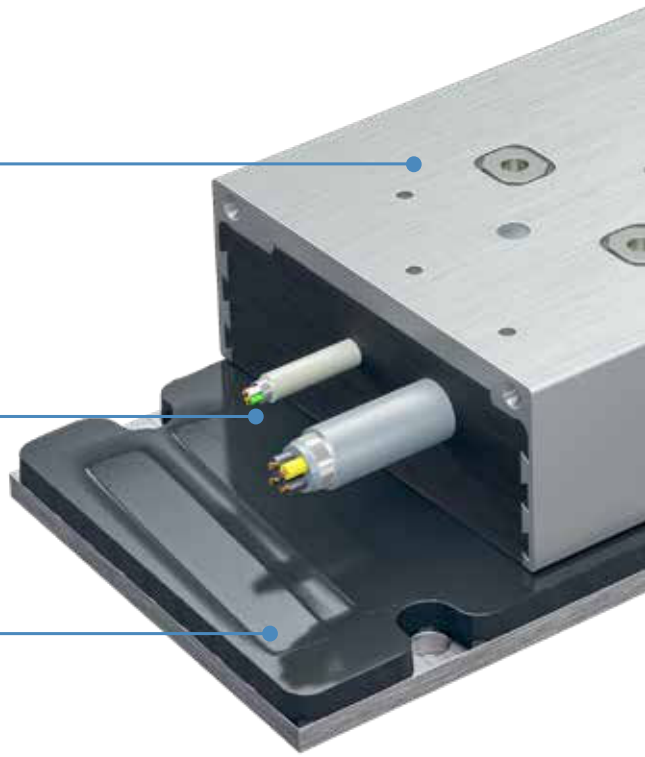
Enhanced thermal management

Low thermal resistance (R_{th})

Power and sensor cable

Temperature measurement and cut-off sensor

NdFeB magnets



Magnet

unit

Lifetime
Proven quality due to in-house testing

Manufacturing
Produced under high quality standards

Aluminum enclosed coil unit

Low thermal resistance
Allowing good heat transfer, achieving an extremely high continuous force for all motors when using a decent size heatsink or active cooling.

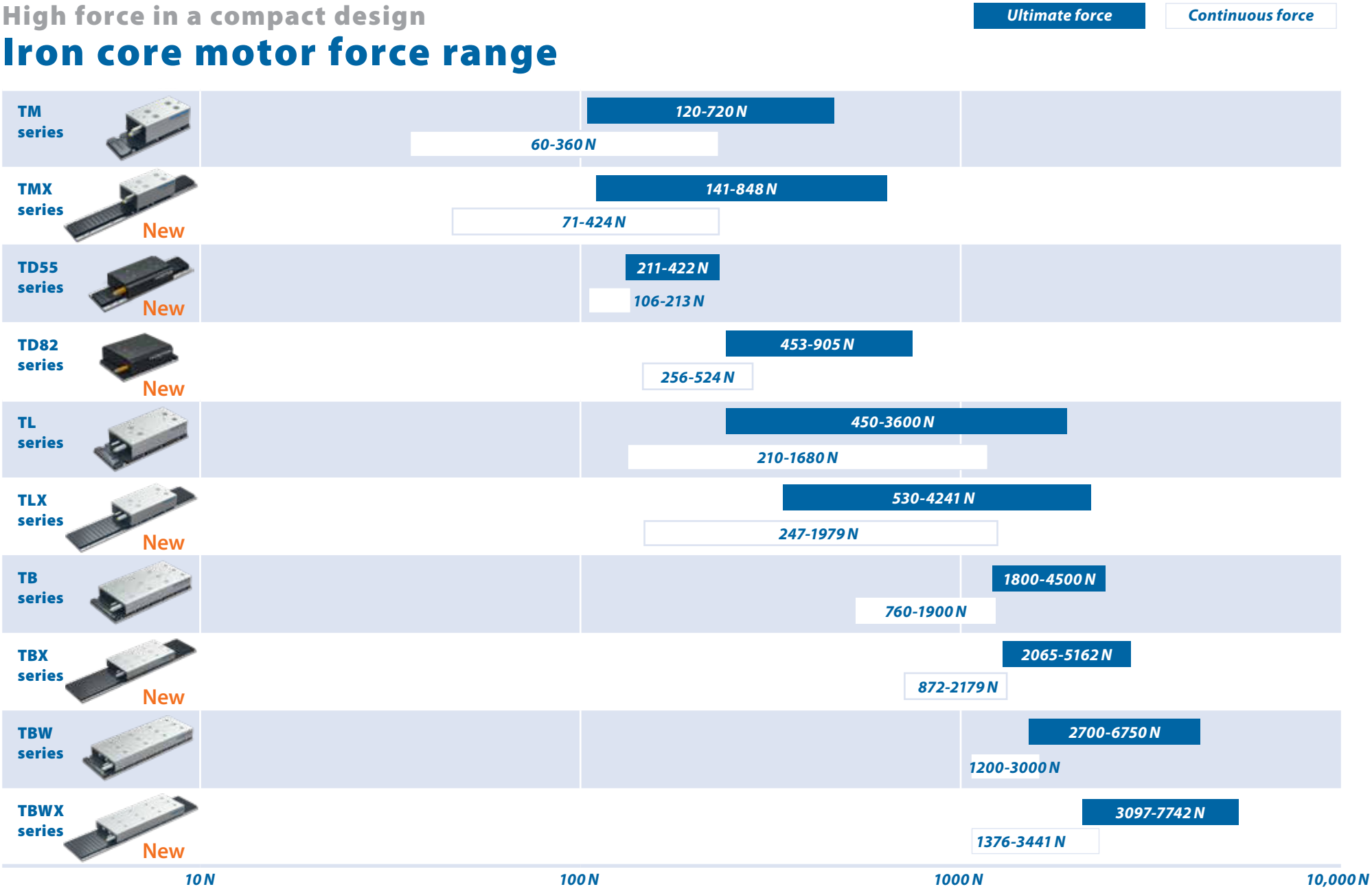
Approved for CSA, CE, UKCA, REACH and RoHS
All iron core motors from Tecnotion are approved for CE, CSA, UKCA, REACH, and RoHS. (REACH and RoHS for the TxX and TD series, expected in 2025).

Magnet field protection plates
Enhanced safety and efficient handling of the magnet plates when installing the plates within your application.

plate

High force in a compact design

Iron core motor force range



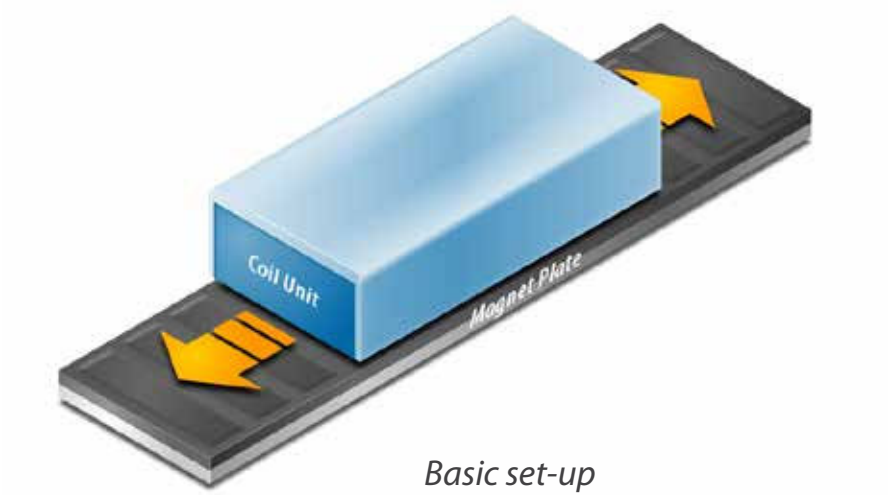
TECNOTION
direct drive in motion

Modular
Motor configurations

The direct drive technology of iron core linear motors is a perfect way to enhance productivity, accuracy, and dynamic performance. Linear motors eliminate the need for mechanical transmissions like rack and pinion, belts and speed reducers. Between coil unit and magnets there is no contact, this means no mechanical wear. The technology makes designs slimmer, modular and reduces costs.

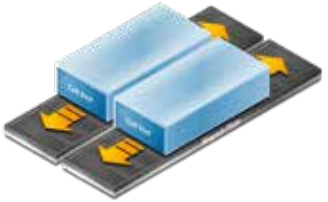
Motors can be mechanically aligned in series or parallel. This allows motors to move on different tracks, distributing even force to a large gantry, or on the same track, enhancing power along a single line. In both cases, the total force of all motors adds up. Standardizing coil assemblies across multiple machines and applications reduces expenses and simplifies field support.

MODULAR SYSTEM All motors can be used in various configurations

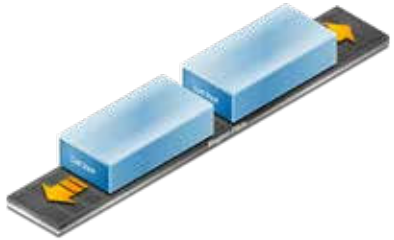


Basic set-up

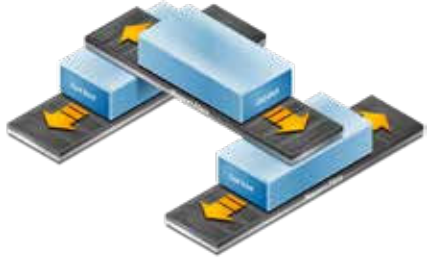
Moving magnet



Parallel coupled coil



In-line on a single plate



Cross table or gantry

TM series

TM3 on 144mm magnet plate

	Parameter	Remarks	Symbol	Unit	TM3		TM6		TM12	TM18	
Performance	Winding type				S	Z	S	Z	S	N	S
	Motor type, max voltage ph-ph	3-phase synchronous	U_{max}	$V_{ac,rms}$ (V_{dc})	400 (565)						
	Ultimate force @ 10 K/s increase	magnets @ 25°C	F_u	N	120		240		480	720	
	Peak force @ 6 K/s increase	magnets @ 25°C	F_p	N	105		210		420	630	
	Continuous force[1]	coils @ 100°C	F_c	N	60		120		240	360	
	Maximum speed[2]	@ U_{max} @ F_c	v_{max}	m/s	11	32	11	32	11	5.5	11
	Motor force constant	$I \leq I_c$	K_f	N/A_{rms}	39	12.9	39	12.9	39	79	39
	Motor constant	coils @ 25°C	S	N^2/W	94	99	188	198	376	578	596
Electrical	Ultimate current	magnets @ 25°C	I_u	A_{rms}	4.1	12.6	8.2	25.1	16.4	12.3	25.1
	Peak current	magnets @ 25°C	I_p	A_{rms}	3.1	9.5	6.2	18.9	12.4	9.2	18.9
	Continuous current[1]	coils @ 100°C	I_c	A_{rms}	1.5	4.7	3.0	9.3	6.0	4.5	9.3
	Back EMF ph-ph$_{peak}$		K_e	V_{dc}/m/s	32	11	32	11	32	65	32
	Resistance per phase	coils @ 25°C ex. cable	R_{ph}	Ω	5.4	0.56	2.7	0.28	1.35	3.6	0.85
	Induction per phase	$I < 0.6\ I_p$	L_{ph}	mH	35	3.7	17	1.8	8.7	23	5.5
	Electrical time constant		τ_e	ms	6.5						
Thermal	Continuous power loss[1]	coils @ 100°C	P_c	W	49		99		197	296	
	Thermal resistance	coils to mount. sfc.	R_{th}	K/W	1.5		0.75		0.38	0.25	
	Thermal time constant		τ_{th}	s	75						
	Temperature sensor				PTC 1kΩ / KTY 83-122						
Mechanical	Coil unit mass	ex. cables	m	kg	0.6		0.9		1.6	2.3	
	Coil unit length	ex. cables	L	mm	93		143		241	336	
	Motor attraction force	rms @ 0 A	F_a	N	300		500		900	1300	
	Magnet pitch NN		τ	mm	24						
	Cable mass	all cables		kg/m	0.18						
	Cable type (power FLEX)	length 3 m	d	mm (AWG)	8.3 (18)						
	Cable type (sensor)	length 3 m	d	mm (AWG)	4.7 (26)						
	Cable life (power FLEX)[3]	minimum		cycles	5,000,000						
	Bending radius static (power FLEX)	minimum			4x cable diameter						
	Bending radius dynamic (power FLEX)	minimum			10x cable diameter						

All specifications ±10%

[1] *These values are only applicable when the mounting surface is at 20°C and the motor is driven at continuous current. If these values differ in your application, please check our simulation tool.*
[2] *Actual values depend on bus voltage. Please check the F/v diagram in our simulation tool.*
[3] *Depending on bending radius, velocity and acceleration.*

FLEX cable

The TM series comes standard with a 3m long FLEX power cable.

Magnet plate dimensions

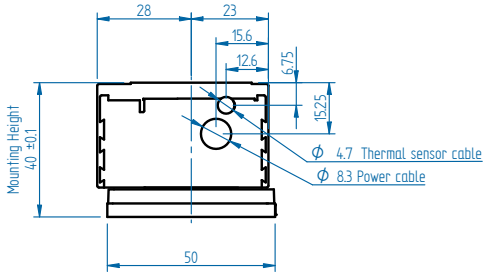
Le (mm)	96	144	384
M5 bolts	4	6	16
Mass (kg/m)		2.1	

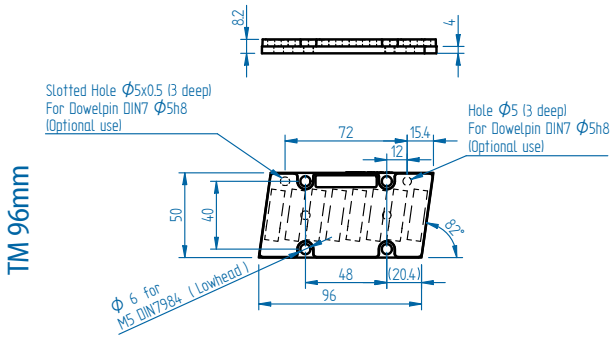
Magnet plates can be butted together.

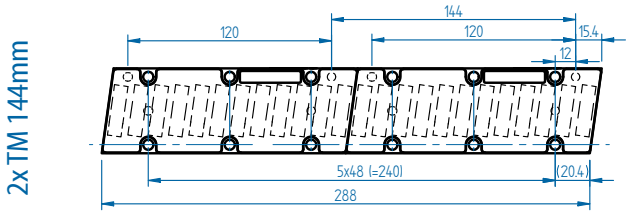
Approvals

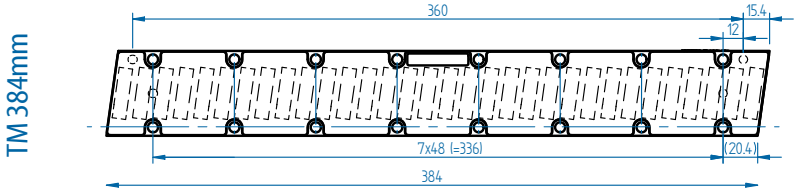
TECNOTION direct drive in motion

Magnet plates

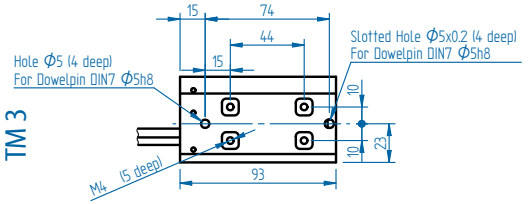


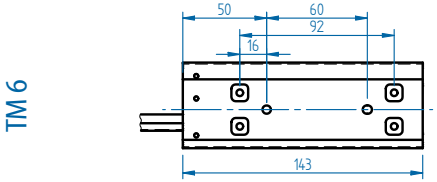


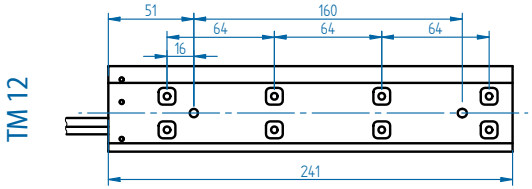


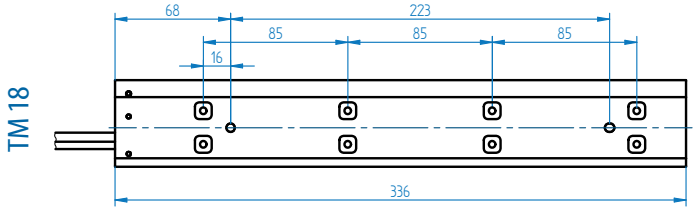


Coil units





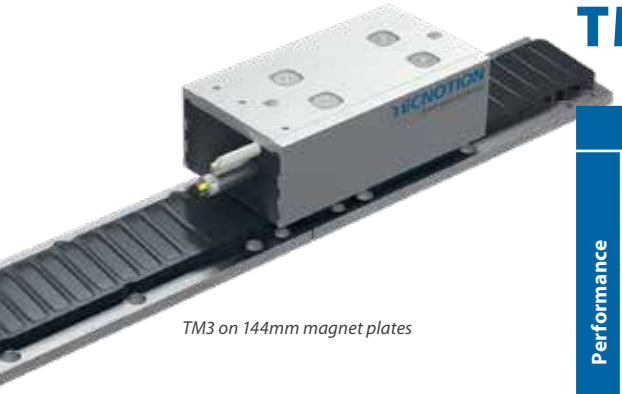




Mounting instructions and flatness or parallelism requirements can be found in the iron core installation manual. CAD files, 3D models and the manual can be downloaded from our website.

** All sizes are in mm*

TMX series



TM3 on 144mm magnet plates

	Parameter	Remarks	Symbol	Unit	TMX3		TMX6		TMX12	TMX18	
Performance	Winding type				S	Z	S	Z	S	N	S
	Motor type, max voltage ph-ph	3-phase synchronous	U_{max}	$V_{ac,rms}$ (V_{dc})	400 (565)						
	Ultimate force @ 10 K/s increase	magnets @ 25°C	F_u	N	141		283		565	848	
	Peak force @ 6 K/s increase	magnets @ 25°C	F_p	N	124		247		495	742	
	Continuous force[1]	coils @ 100°C	F_c	N	71		141		283	424	
	Maximum speed[2]	@ U_{max} @ F_c	v_{max}	m/s	10	32	10	32	10	5.1	10
	Motor force constant	$I \leq I_c$	K_f	N/A_{rms}	46	15	46	15	46	93	46
	Motor constant	coils @ 25°C	S	N^2/W	130	137	261	275	522	802	827
Electrical	Ultimate current	magnets @ 25°C	I_u	A_{rms}	4.1	12.6	8.2	25.1	16.4	12.3	25.1
	Peak current	magnets @ 25°C	I_p	A_{rms}	3.1	9.5	6.2	18.9	12.4	9.2	18.9
	Continuous current[1]	coils @ 100°C	I_c	A_{rms}	1.5	4.7	3.0	9.3	6.0	4.5	9.3
	Back EMF ph-ph$_{peak}$		K_e	V_{dc}/m/s	38	13	38	13	38	77	38
	Resistance per phase	coils @ 25°C ex. cable	R_{ph}	Ω	5.4	0.56	2.7	0.28	1.35	3.6	0.85
	Induction per phase	$I < 0.6\ I_p$	L_{ph}	mH	36.1	3.8	17.5	1.9	9.0	24	5.7
	Electrical time constant		τ_e	ms	6.7						
Thermal	Continuous power loss[1]	coils @ 100°C	P_c	W	49		99		197	296	
	Thermal resistance	coils to mount. sfc.	R_{th}	K/W	1.5		0.75		0.38	0.25	
	Thermal time constant		τ_{th}	s	75						
	Temperature sensor				PTC 1kΩ / KTY 83-122						
Mechanical	Coil unit mass	ex. cables	m	kg	0.6		0.9		1.6	2.3	
	Coil unit length	ex. cables	L	mm	93		143		241	336	
	Motor attraction force	rms @ 0 A	F_a	N	400		700		1250	1800	
	Magnet pitch NN		τ	mm	24						
	Cable mass	all cables		kg/m	0.18						
	Cable type (power FLEX)	length 3 m	d	mm (AWG)	8.3 (18)						
	Cable type (sensor)	length 3 m	d	mm (AWG)	4.7 (26)						
	Cable life (power FLEX)[3]	minimum		cycles	5,000,000						
	Bending radius static (power FLEX)	minimum			4x cable diameter						
	Bending radius dynamic (power FLEX)	minimum			10x cable diameter						

All specifications ±10%

[1] *These values are only applicable when the mounting surface is at 20°C and the motor is driven at continuous current. If these values differ in your application, please check our simulation tool.*

[2] *Actual values depend on bus voltage. Please check the F/v diagram in our simulation tool.*

[3] *Depending on bending radius, velocity and acceleration.*

FLEX cable

The TM series comes standard with a 3m long FLEX power cable.

Magnet plate dimensions

Le (mm)	96	144	384
M5 bolts	4	6	16
Mass (kg/m)		2.3	

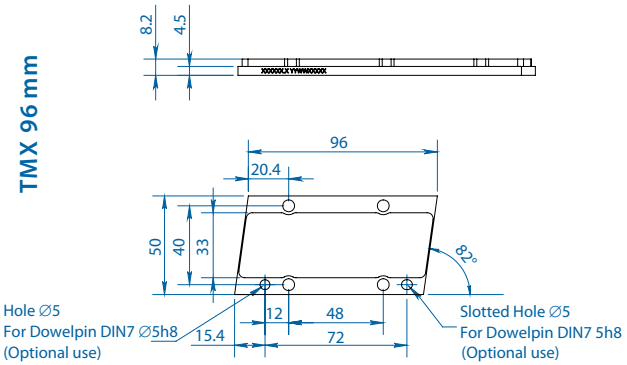
Magnet plates can be butted together.

Approvals

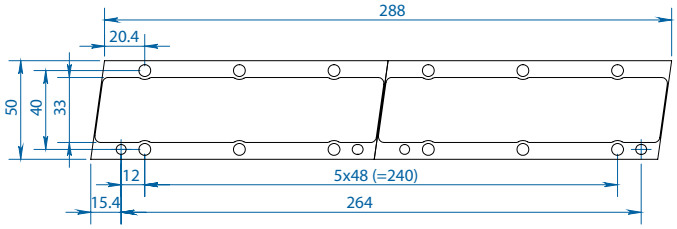
** Expected in 2025.*

Magnet plates

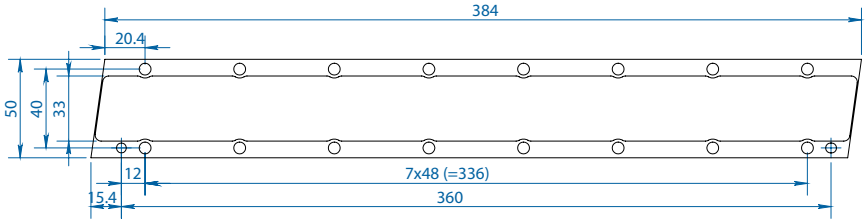
TMX 96 mm

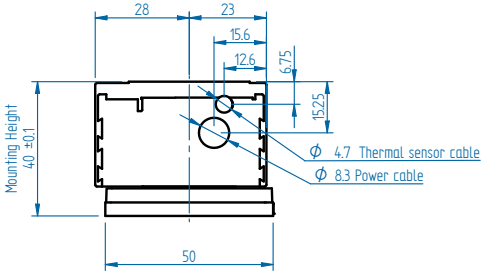


2x TMX 144 mm



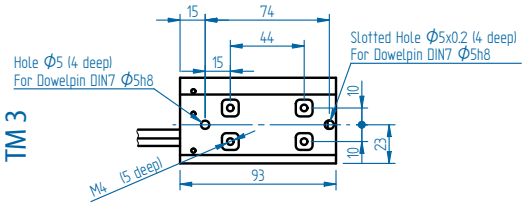
TMX 384 mm



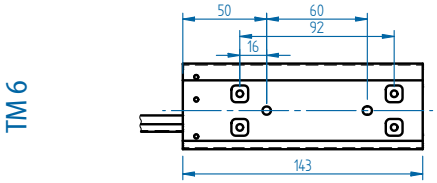


Coil units

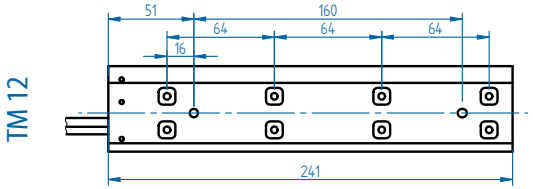
TM 3



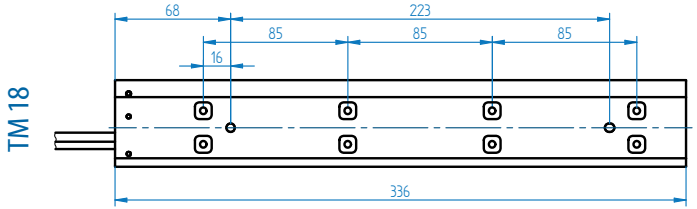
TM 6



TM 12



TM 18



Mounting instructions and flatness or parallelism can be found in the iron core installation manual, and are not different from the standard magnet plate. CAD files, 3D models and the manual can be downloaded from our website.

** All sizes are in mm*

TL series

TL6 on 192mm magnet plate

Parameter	Remarks	Sym	Unit	TL6		TL9		TL12		TL15		TL18		TL24		TL48
Performance																
Winding type				N	S	N	S	N	S	N	S	N	S	N	S	Q
Motor type, max voltage ph-ph	3-phase synchronous	U_{max}	$V_{ac,rms}$ (V_{dc})	400 (565)												
Ultimate force @ 10 K/s increase	magnets @ 25°C	F_u	N	450		675		900		1125		1350		1800		3600
Peak force @ 6 K/s increase	magnets @ 25°C	F_p	N	400		600		800		1000		1200		1600		3200
Continuous force water cooled[1]	coils @ 100°C	F_{cw}	N	210		315		420		525		630		840		1680
Continuous force[1]	coils @ 100°C	F_c	N	200		300		400		500		600		800		1600
Maximum speed[2]	@ U_{max} @ F_c	v_{max}	m/s	4.8	9.4	3.1	9.4	4.8	9.4	3.9	9.4	4.8	9.8	4.8	9.4	2.4
Motor force constant	$I \leq I_c$	K_f	N/A_{rms}	93	46.5	140	46.5	93	46.5	112	46.5	93	44.9	93	46.5	180
Motor constant	coils @ 25°C	S	N^2/W	400	400	605	596	801	801	972	1001	1196	1139	1593	1567	3130
Electrical																
Ultimate current	magnets @ 25°C	I_u	A_{rms}	6.5	13.1	6.5	19.6	13.1	26.2	13.5	32.7	19.6	40.6	26.2	52.3	27.1
Peak current	magnets @ 25°C	I_p	A_{rms}	5.0	10.0	5.0	15.0	10.0	20.0	10.4	25.0	15.0	31.0	20.0	40.0	20.7
Continuous current water cooled[1]	coils @ 100°C	I_{cw}	A_{rms}	2.26	4.5	2.26	6.8	4.5	9.0	4.7	11.3	6.8	14.0	9.0	18.1	9.4
Back EMF ph-ph$_{peak}$		K_e	V_{dc}/m/s	76	38	114	38	76	38	92	38	76	38	76	38	147
Resistance per phase	coils @ 25°C ex. cable	R_{ph}	Ω	7.2	1.80	10.8	1.21	3.6	0.90	4.3	0.72	2.41	0.59	1.81	0.46	3.45
Induction per phase	$I < 0.6\ I_p$	L_{ph}	mH	54	14	81	9.0	27	7.0	32	5.4	18	4.4	14	3.4	26
Electrical time constant		τ_e	ms	7.5												
Thermal																
Continuous power loss[1]	coils @ 100°C	P_c	W	150		225		300		375		450		600		1200
Thermal resistance	coils to mount. sfc.	R_{th}	K/W	0.48		0.32		0.24		0.19		0.16		0.12		0.06
Thermal time constant		τ_{th}	s	77												
Water cooling flow	for ΔT=3K	Φ_w	l/min	0.7		1.1		1.4		1.8		2.2		2.9		5.7
Water cooling pressure drop		ΔP_w	bar	1				2						3		7
Temperature sensor				PTC 1kΩ / KTY 83-122												
Mechanical																
Coil unit mass	ex. cables	m	kg	1.5		2.0		2.6		3.2		3.8		5.2		9.8
Coil unit length	ex. cables	L	mm	146		194		244		290		336		468		855
Motor attraction force	rms @ 0 A	F_a	N	950		1325		1700		2075		2450		3400		6400
Magnet pitch NN		τ	mm	24												
Cable mass	all cables		kg/m	0.18										0.3		
Cable type (power)	length 1 m	d	mm (AWG)	9.6 (18)										11.4 (14)		
Cable type (sensor)	length 1 m	d	mm (AWG)	4.7 (26)												

All specifications ±10%

[1] *These values are only applicable when the mounting surface is at 20°C and the motor is driven at continuous current. If these values differ in your application, please check our simulation tool.*

[2] *Actual values depend on bus voltage. Please check the F/v diagram in our simulation tool.*

Water cooling

All TL motors feature integrated cooling channels that allow for the easy setup of a liquid cooled system, at no additional cost.

Magnet plate dimensions

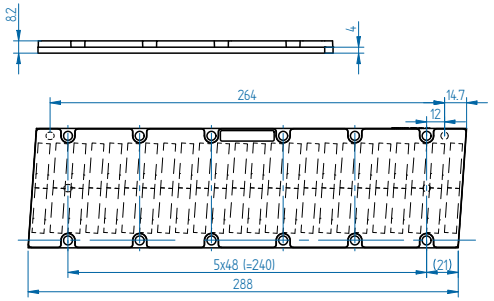
Le (mm)	192	288
M5 bolts	8	12
Mass (kg/m)	3.8	

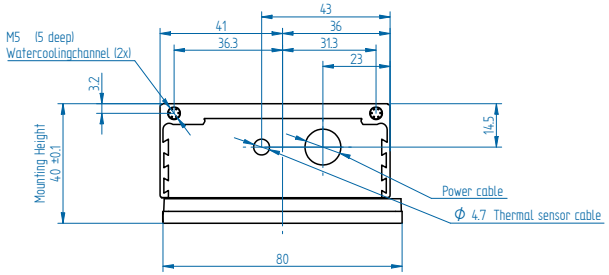
Magnet plates can be butted together.

Approvals

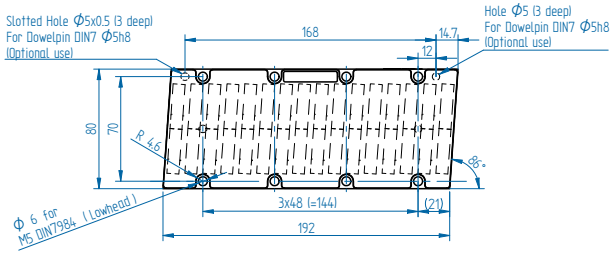
Magnet plates

TL 192 mm

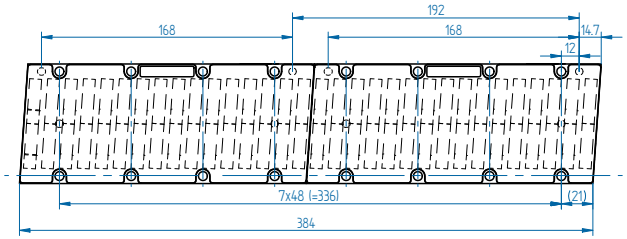




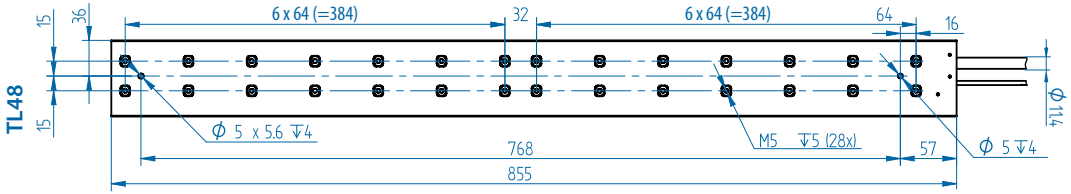
TL 288 mm



2x TL 192 mm

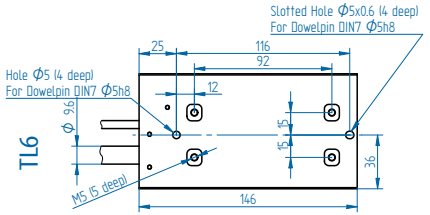


TL48

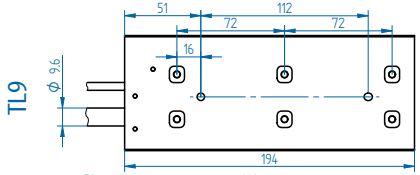


Coil units

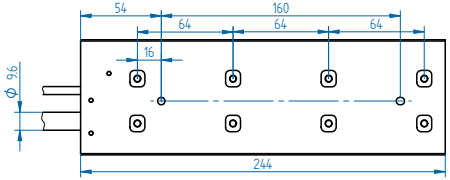
TL6



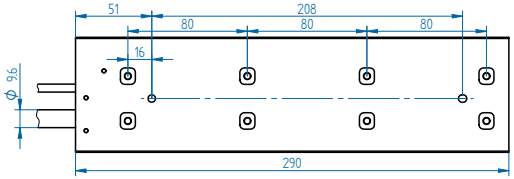
TL9



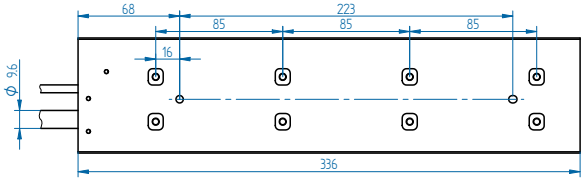
TL12



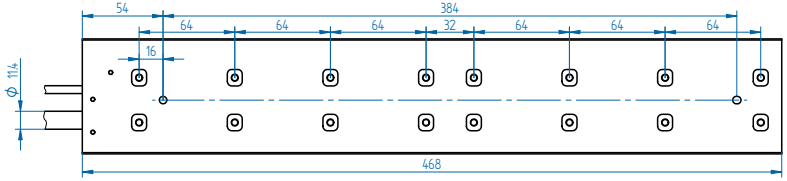
TL15



TL18



TL24



Mounting instructions and flatness or parallelism requirements can be found in the iron core installation manual. CAD files, 3D models and the manual can be downloaded from our website.

** All sizes are in mm*

TLX series

TL6 on TLX 192mm magnet plates

	Parameter	Remarks	Sym	Unit	TLX6		TLX9		TLX12		TLX15		TLX18		TLX24		TLX48
Performance	Winding type				N	S	N	S	N	S	N	S	N	S	N	S	Q
	Motor type, max voltage ph-ph	3-phase synchronous	U_{max}	$V_{ac,rms}$ (V_{dc})	400 (565)												
	Ultimate force @ 10 K/s increase	magnets @ 25°C	F_u	N	530		795		1060		1325		1590		2120		4241
	Peak force @ 6 K/s increase	magnets @ 25°C	F_p	N	471		707		942		1178		1414		1885		3770
	Continuous force water cooled[1]	coils @ 100°C	F_{cw}	N	247		371		495		618		742		990		1979
	Continuous force[1]	coils @ 100°C	F_c	N	236		353		471		589		707		942		1885
	Maximum speed[2]	@ U_{max} @ F_c	v_{max}	m/s	4.4	8.8	2.9	8.8	4.4	8.8	3.6	8.8	4.4	9.2	4.4	8.8	2.1
	Motor force constant	$I \leq I_c$	K_f	N/A_{rms}	110	55	165	55	110	55	132	55	110	53	110	55	212
	Motor constant	coils @ 25°C	S	N^2/W	556	556	839	827	1111	1111	1349	1389	1660	1581	2210	2174	4344
Electrical	Ultimate current	magnets @ 25°C	I_u	A_{rms}	6.5	13.1	6.5	19.6	13.1	26.2	13.5	32.7	19.6	41.0	26.2	52.0	27.1
	Peak current	magnets @ 25°C	I_p	A_{rms}	5.0	10.0	5.0	15.0	10.0	20.0	10.4	25.0	15.0	31.0	20.0	40.0	20.7
	Continuous current water cooled[1]	coils @ 100°C	I_{cw}	A_{rms}	2.26	4.5	2.26	6.8	4.5	9.0	4.7	11.3	6.8	14.0	9.0	18.1	9.4
	Back EMF ph-ph$_{peak}$		K_e	V_{dc}/m/s	90	45	134	45	90	45	108	45	90	45	90	45	173
	Resistance per phase	coils @ 25°C ex. cable	R_{ph}	Ω	7.2	1.80	10.8	1.21	3.6	0.90	4.3	0.72	2.41	0.59	1.81	0.46	3.45
	Induction per phase	$I < 0.6\ I_p$	L_{ph}	mH	56	14.4	83	9.3	28	7.2	33	5.6	18.5	4.5	14.4	3.5	27
	Electrical time constant		τ_e	ms	7.7												
Thermal	Continuous power loss[1]	coils @ 100°C	P_c	W	150		225		300		375		450		600		1200
	Thermal resistance	coils to mount. sfc.	R_{th}	K/W	0.48		0.32		0.24		0.19		0.16		0.12		0.06
	Thermal time constant		τ_{th}	s	77												
	Water cooling flow	for ΔT=3K	Φ_w	l/min	0.7		1.1		1.4		1.8		2.2		2.9		5.7
	Water cooling pressure drop		ΔP_w	bar	1				2						3		7
	Temperature sensor				PTC 1kΩ / KTY 83-122												
Mechanical	Coil unit mass	ex. cables	m	kg	1.5		2.0		2.6		3.2		3.8		5.2		9.8
	Coil unit length	ex. cables	L	mm	146		194		244		290		336		468		855
	Motor attraction force	rms @ 0 A	F_a	N	1300		1800		2350		2850		3350		4650		8750
	Magnet pitch NN		τ	mm	24												
	Cable mass	all cables		kg/m	0.18										0.3		
	Cable type (power)	length 1 m	d	mm (AWG)	9.6 (18)										11.4 (14)		
	Cable type (sensor)	length 1 m	d	mm (AWG)	4.7 (26)												

All specifications ±10%

[1] *These values are only applicable when the mounting surface is at 20°C and the motor is driven at continuous current. If these values differ in your application, please check our simulation tool.*

[2] *Actual values depend on bus voltage. Please check the F/v diagram in our simulation tool.*

Water cooling

All TL motors feature integrated cooling channels that allow for the easy setup of a liquid cooled system, at no additional cost.

Magnet plate dimensions

Le (mm)	192	288
M5 bolts	8	12
Mass (kg/m)	4.0	

Magnet plates can be butted together.

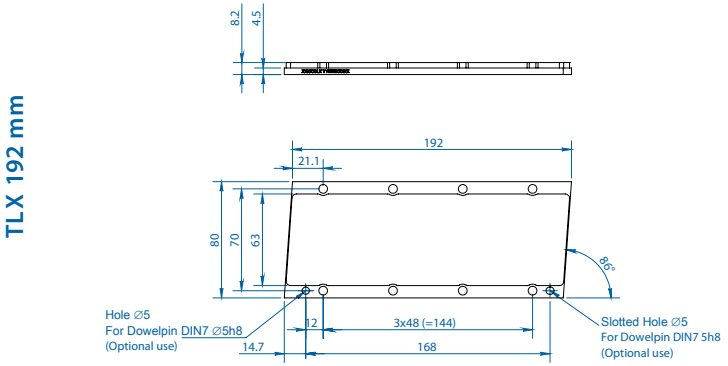
Approvals

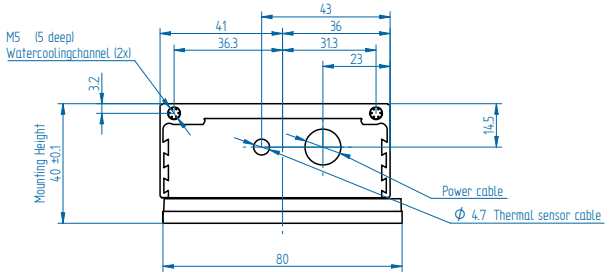
** Expected in 2025.*

TECNOTION direct drive in motion

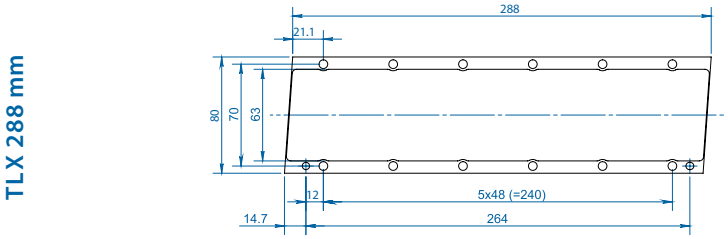
Magnet plates

TLX 192 mm

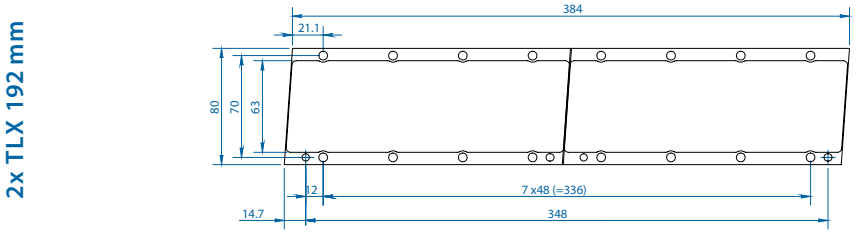




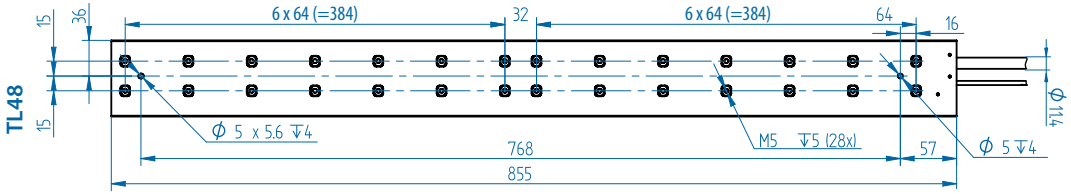
TLX 288 mm



2x TLX 192 mm

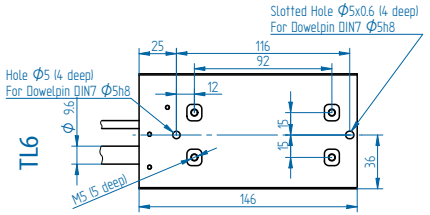


TL48

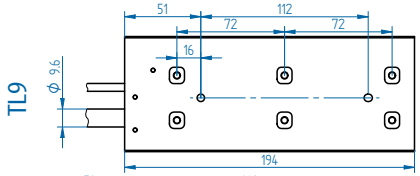


Coil units

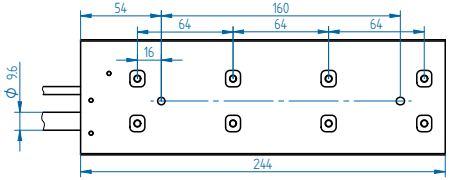
TL6



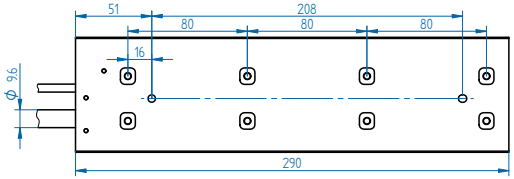
TL9



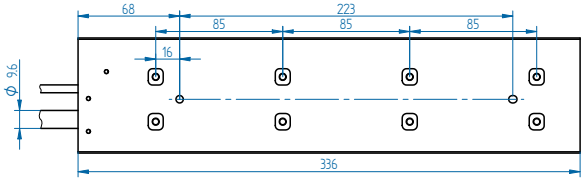
TL12



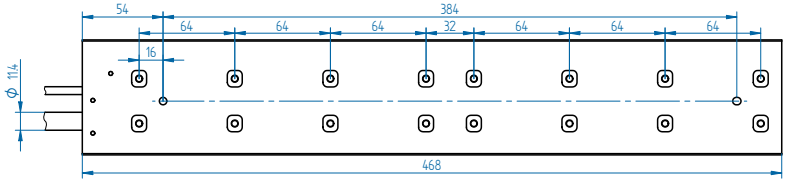
TL15



TL18



TL24



Mounting instructions and flatness or parallelism can be found in the iron core installation manual, and are not different from the standard magnet plate. CAD files, 3D models and the manual can be downloaded from our website.

** All sizes are in mm*

TB series

TB12 on 288mm magnet plate

Magnet plate dimensions		
Le (mm)	192	288
M5 bolts	8	12
Mass (kg/m)	10.5	
Magnet plates can be butted together.		

Approvals

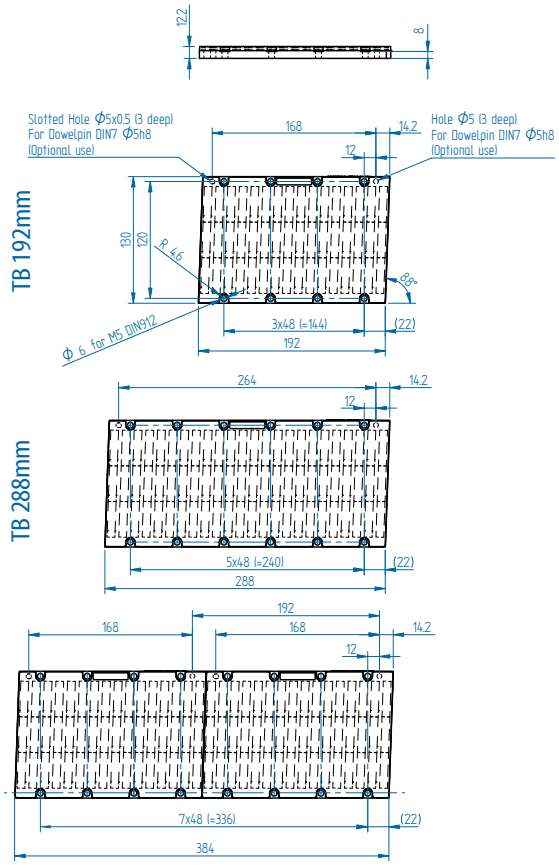
	Parameter	Remarks	Sym	Unit	TB12		TB15		TB18	TB24	TB30	
Performance	Winding type				N	S	N	S	N	N	N	S
	Motor type, max voltage ph-ph	3-phase synchronous	U_{max}	$V_{ac,rms}$ (V_{dc})	400 (565)							
	Ultimate force @ 10 K/s increase	magnets @ 25°C	F_u	N	1800		2250		2700	3600	4500	
	Peak force @ 6 K/s increase	magnets @ 25°C	F_p	N	1600		2000		2400	3200	4000	
	Continuous force[1]	coils @ 100°C	F_c	N	760		950		1140	1520	1900	
	Maximum speed[2]	@ U_{max} @ F_c	v_{max}	m/s	2.4	5.0	2.0	5.0	2.4	1.9	2.0	5.0
	Motor force constant	$I \leq I_c$	K_f	N/A_{rms}	186	93	225	93	186	232	225	93
	Motor constant	coils @ 25°C	S	N^2/W	1830	1802	2220	2218	2746	3588	4441	4435
Electrical	Ultimate current	magnets @ 25°C	I_u	A_{rms}	13.0	26	13.5	33	20	21	27	66
	Peak current	magnets @ 25°C	I_p	A_{rms}	10.0	20	10.0	25	15	16	20	50
	Continuous current[1]	coils @ 100°C	I_c	A_{rms}	4.1	8.2	4.2	10.2	6.1	6.6	8.5	20.5
	Back EMF ph-ph_{peak}		K_e	V_{dc}/m/s	152	76	183	76	152	189	183	76
	Resistance per phase	coils @ 25°C ex. cable	R_{ph}	Ω	6.3	1.6	7.6	1.3	4.2	5.0	3.8	0.65
	Induction per phase	$I < 0.6\ I_p$	L_{ph}	mH	51	13	60	10	34	40	30	5.1
	Electrical time constant		τ_e	ms	8.0							
Thermal	Continuous power loss[1]	coils @ 100°C	P_c	W	430		530		640	853	1060	
	Thermal resistance	coils to mount. sfc.	R_{th}	K/W	0.15		0.12		0.11	0.08	0.06	
	Thermal time constant		τ_{th}	s	90							
	Temperature sensor				PTC 1kΩ / KTY 83-122							
Mechanical	Coil unit mass	ex. cables	m	kg	4.9		5.9		6.9	9.4	11.6	
	Coil unit length	ex. cables	L	mm	244		290		336	434	562	
	Motor attraction force	rms @ 0 A	F_a	N	3400		4150		4900	6800	8300	
	Magnet pitch NN		τ	mm	24							
	Cable mass	all cables		kg/m	0.3							
	Cable type (power)	length 1 m	d	mm (AWG)	11.4 (14)							
	Cable type (sensor)	length 1 m	d	mm (AWG)	4.7 (26)							

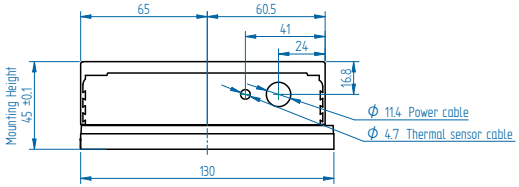
All specifications ±10%

[1] *These values are only applicable when the mounting surface is at 20°C and the motor is driven at continuous current. If these values differ in your application, please check our simulation tool.*

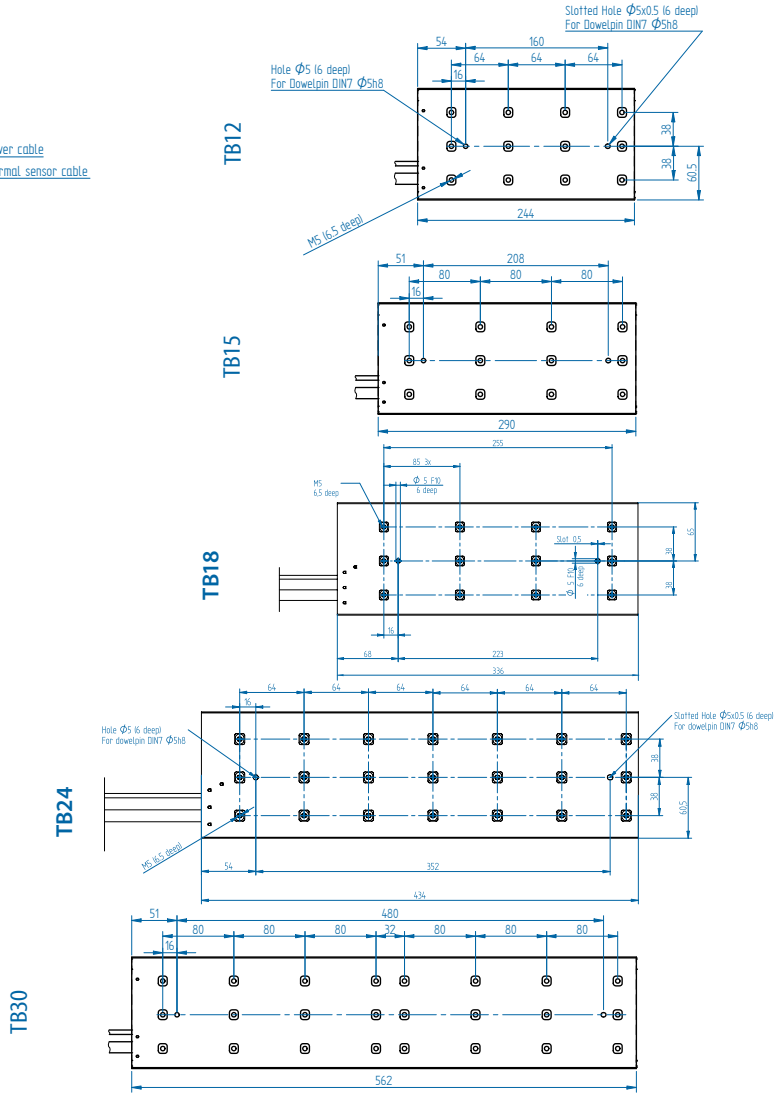
[2] *Actual values depend on bus voltage. Please check the F/v diagram in our simulation tool.*

Magnet plates





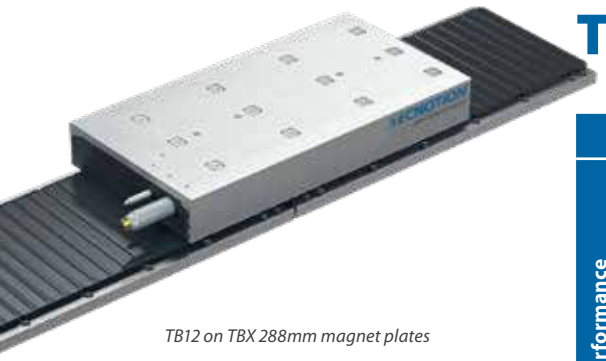
Coil units



Mounting instructions and flatness or parallelism requirements can be found in the iron core installation manual. CAD files, 3D models and the manual can be downloaded from our website.

** All sizes are in mm*

TBX series



TB12 on TBX 288mm magnet plates

Parameter	Remarks	Sym	Unit	TBX12		TBX15		TBX18	TBX24	TBX30	
Performance											
Winding type				N	S	N	S	N	N	N	S
Motor type, max voltage ph-ph	3-phase synchronous	U_{max}	$V_{ac,rms}$ (V_{dc})	400 (565)							
Ultimate force @ 10 K/s increase	magnets @ 25°C	F_u	N	2065		2581		3097	4129	5162	
Peak force @ 6 K/s increase	magnets @ 25°C	F_p	N	1835		2294		2753	3670	4588	
Continuous force[1]	coils @ 100°C	F_c	N	872		1090		1308	1743	2179	
Maximum speed[2]	@ U_{max} @ F_c	v_{max}	m/s	2.2	4.7	1.8	4.7	2.2	1.7	1.8	4.7
Motor force constant	$I \leq I_c$	K_f	N/A_{rms}	213	107	258	107	213	266	258	107
Motor constant	coils @ 25°C	S	N^2/W	2408	2371	2921	2921	3613	4721	5842	5835
Electrical											
Ultimate current	magnets @ 25°C	I_u	A_{rms}	13.0	26	13.5	33	20	21	27	66
Peak current	magnets @ 25°C	I_p	A_{rms}	10.0	20	10.0	25	15	16	20	50
Continuous current[1]	coils @ 100°C	I_c	A_{rms}	4.1	8.2	4.2	10.2	6.1	6.6	8.5	20.5
Back EMF ph-ph$_{peak}$		K_e	V_{dc}/m/s	174	87	210	87	174	217	210	87
Resistance per phase	coils @ 25°C ex. cable	R_{ph}	Ω	6.3	1.6	7.6	1.3	4.2	5.0	3.8	0.65
Induction per phase	$I < 0.6\ I_p$	L_{ph}	mH	53	13.4	62	10.3	35	41	31	5.3
Electrical time constant		τ_e	ms	8.2							
Thermal											
Continuous power loss[1]	coils @ 100°C	P_c	W	430		530		640	853	1060	
Thermal resistance	coils to mount. sfc.	R_{th}	K/W	0.15		0.12		0.11	0.08	0.06	
Thermal time constant		τ_{th}	s	90							
Temperature sensor				PTC 1kΩ / KTY 83-122							
Mechanical											
Coil unit mass	ex. cables	m	kg	4.9		5.9		6.9	9.4	11.6	
Coil unit length	ex. cables	L	mm	244		290		336	434	562	
Motor attraction force	rms @ 0 A	F_a	N	4400		5350		6300	8750	10700	
Magnet pitch NN		τ	mm	24							
Cable mass	all cables		kg/m	0.3							
Cable type (power)	length 1 m	d	mm (AWG)	11.4 (14)							
Cable type (sensor)	length 1 m	d	mm (AWG)	4.7 (26)							

All specifications ±10%

[1] *These values are only applicable when the mounting surface is at 20°C and the motor is driven at continuous current. If these values differ in your application, please check our simulation tool.*

[2] *Actual values depend on bus voltage. Please check the F/v diagram in our simulation tool.*

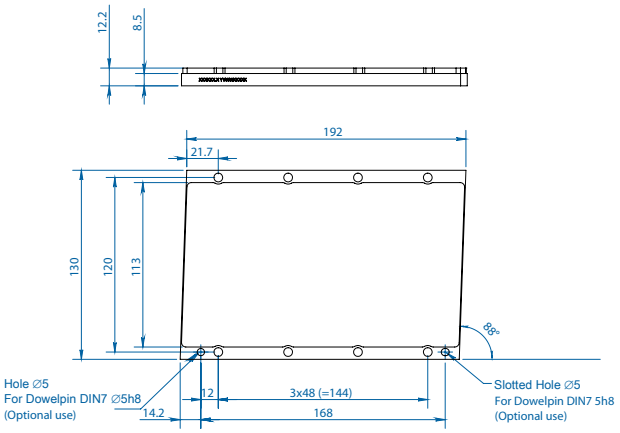
Magnet plate dimensions		
Le (mm)	192	288
M5 bolts	8	12
Mass (kg/m)	10.8	
Magnet plates can be butted together.		

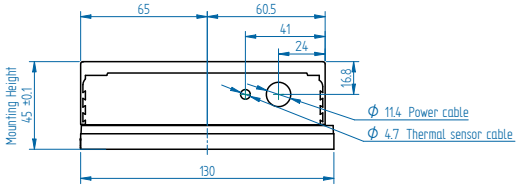
Approvals

** Expected in 2025.*

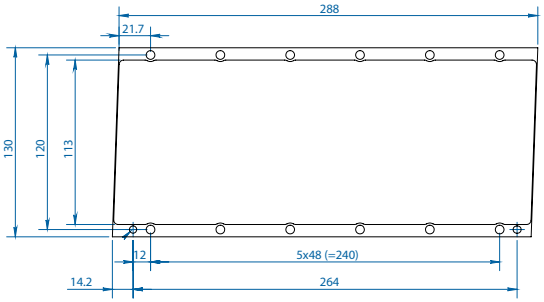
Magnet plates

TBX 192 mm

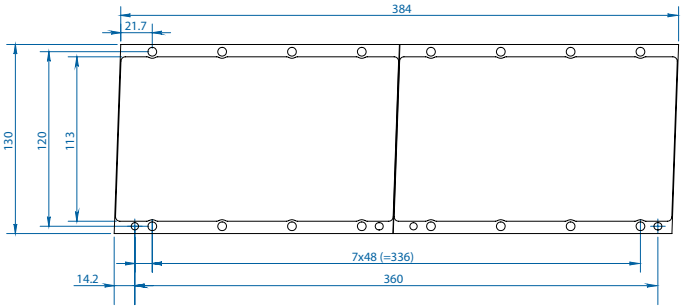




TBX 288 mm

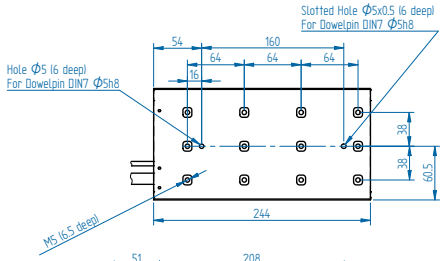


2x TBX 192 mm

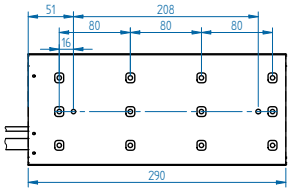


Coil units

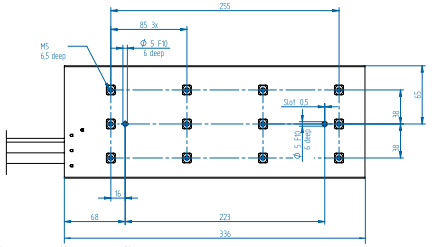
TB12



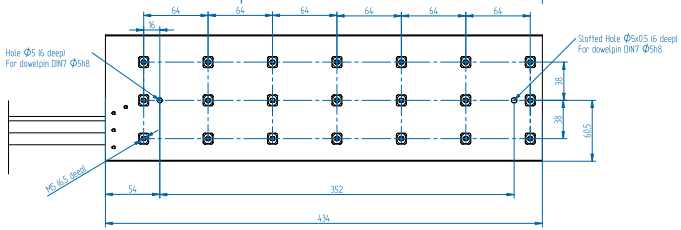
TB15



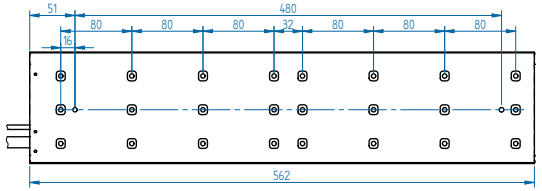
TB18



TB24



TB30



Mounting instructions and flatness or parallelism can be found in the iron core installation manual, and are not different from the standard magnet plate. CAD files, 3D models and the manual can be downloaded from our website.

** All sizes are in mm*

TBW series

TBW18 on 192mm magnet plates

Parameter	Remarks	Symbol	Unit	TBW18		TBW30		TBW45	
				N	S	N	S	N	S
Performance									
Winding type									
Motor type, max voltage ph-ph	3-phase synchronous	U_{max}	$V_{ac,rms}$ (V_{dc})	400 (565)					
Ultimate force @ 10 K/s increase	magnets @ 25°C	F_u	N	2700		4500		6750	
Peak force @ 6 K/s increase	magnets @ 25°C	F_p	N	2400		4000		6000	
Continuous force water cooled[1]	coils @ 100°C	F_{cw}	N	1200		2000		3000	
Continuous force[1]	coils @ 100°C	F_c	N	1140		1900		2850	
Maximum speed[2]	@ U_{max} @ F_c	v_{max}	m/s	2.4	5.0	2.0	5.0	2.0	5.0
Motor force constant	$I \leq I_c$	K_f	N/A_{rms}	186	90	225	93	225	93
Motor constant	coils @ 25°C	S	N^2/W	2621	2700	4327	4368	6490	6552
Electrical									
Ultimate current	magnets @ 25°C	I_u	A_{rms}	20	41	27	65	41	98
Peak current	magnets @ 25°C	I_p	A_{rms}	15.0	31.1	20.7	50	31.1	75
Continuous current water cooled[1]	coils @ 100°C	I_{cw}	A_{rms}	6.5	13.4	8.9	21.5	13.4	32.3
Back EMF ph-ph $_{peak}$		K_e	V_{dc}/m/s	152	76	183	76	183	76
Resistance per phase	coils @ 25°C ex. cable	R_{ph}	Ω	4.4	1.0	3.9	0.66	2.6	0.44
Induction per phase	$I < 0.6\ I_p$	L_{ph}	mH	35	8.1	31	5.1	21	3.5
Electrical time constant		τ_e	ms	8.0					
Thermal									
Continuous power loss[1]	coils @ 100°C	P_c	W	726		1209		1804	
Thermal resistance	coils to mount. sfc.	R_{th}	K/W	0.10		0.06		0.04	
Thermal time constant		τ_{th}	s	87					
Water cooling flow	for ΔT=3K	Φ_w	l/min	3.1		5.2		7.8	
Water cooling pressure drop		ΔP_w	bar	1.0		1.5		2.5	
Temperature sensor				PTC 1kΩ / KTY 83-122					
Mechanical									
Coil unit mass	ex. cables	m	kg	7.3		12.3		18.2	
Coil unit length	ex. cables	L	mm	344		580		852	
Motor attraction force	rms @ 0 A	F_a	N	4900		8300		12450	
Magnet pitch NN		τ	mm	24					
Cable mass	all cables		kg/m	0.3			0.6		
Cable type (power)	length 1 m	d	mm (AWG)	11.4 (14)			15.8 (10)		
Cable type (sensor)	length 1 m	d	mm (AWG)	4.7 (26)					

All specifications ±10%

[1] *These values are only applicable when the mounting surface is at 20°C and the motor is driven at continuous current. If these values differ in your application, please check our simulation tool.*

[2] *Actual values depend on bus voltage. Please check the F/v diagram in our simulation tool.*

Water cooling

All TBW motors feature integrated cooling channels that allow for the easy setup of a liquid cooled system, at no additional cost.

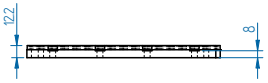
Magnet plate dimensions

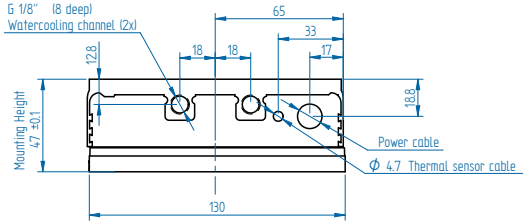
Le (mm)	192	288
M5 bolts	8	12
Mass (kg/m)	10.5	

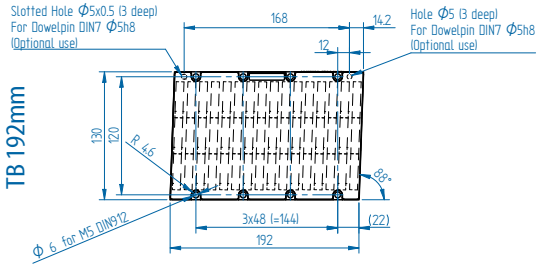
Magnet plates can be butted together.

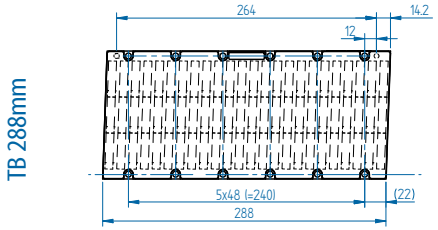
Approvals

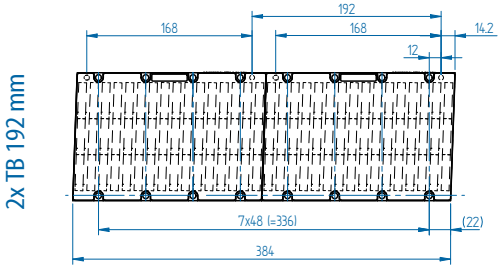
Magnet plates



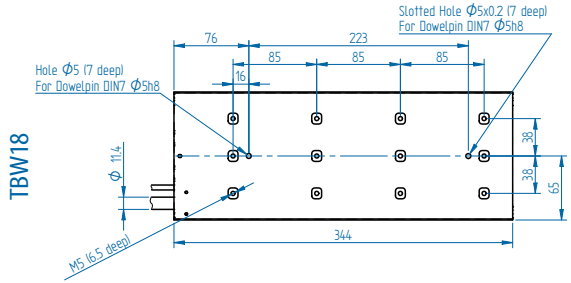


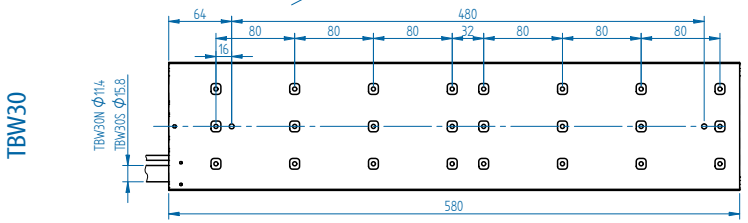


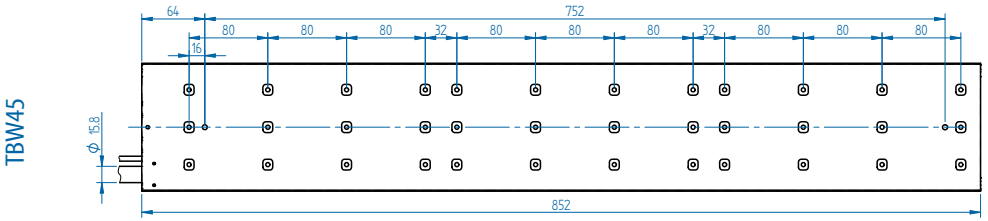




Coil units







Mounting instructions and flatness or parallelism requirements can be found in the iron core installation manual. CAD files, 3D models and the manual can be downloaded from our website.

** All sizes are in mm*

TBWX series

TBW18 on TBX 192mm magnet plates

Parameter	Remarks	Symbol	Unit	TBWX18		TBWX30		TBWX45	
Performance	**Winding type**			N	S	N	S	N	S
	Motor type, max voltage ph-ph	3-phase synchronous	U_{max}	$V_{ac,rms}$ (V_{dc})		400 (565)			
	Ultimate force @ 10 K/s increase	magnets @ 25°C	F_u	N		3097		5162		7742	
	Peak force @ 6 K/s increase	magnets @ 25°C	F_p	N		2753		4588		6882	
	Continuous force water cooled[1]	coils @ 100°C	F_{cw}	N		1376		2294		3441	
	Continuous force[1]	coils @ 100°C	F_c	N		1308		2179		3269	
	Maximum speed[2]	@ U_{max} @ F_c	v_{max}	m/s	2.2	4.9	1.8	4.7	1.8	4.7
	Motor force constant	$I \leq I_c$	K_f	N/A_{rms}	213	103	258	107	258	107
	Motor constant	coils @ 25°C	S	N^2/W	3448	3552	5693	5747	8539	8620
Electrical	**Ultimate current**	magnets @ 25°C	I_u	A_{rms}	20	41	27	65	41	98
	Peak current	magnets @ 25°C	I_p	A_{rms}	15.0	31.1	20.7	50	31.1	75
	Continuous current water cooled[1]	coils @ 100°C	I_{cw}	A_{rms}	6.5	13.4	8.9	21.5	13.4	32.3
	Back EMF ph-ph $_{peak}$		K_e	V_{dc}/m/s	174	87	210	87	210	87
	Resistance per phase	coils @ 25°C ex. cable	R_{ph}	Ω	4.4	1.0	3.9	0.66	2.6	0.44
	Induction per phase	$I < 0.6\ I_p$	L_{ph}	mH	36	8.3	32	5.3	22	3.6
	Electrical time constant		τ_e	ms			8.2			
Thermal	**Continuous power loss**[1]	coils @ 100°C	P_c	W		726		1209		1804
	Thermal resistance	coils to mount. sfc.	R_{th}	K/W		0.10		0.06		0.04
	Thermal time constant		τ_{th}	s			87			
	Water cooling flow	for ΔT=3K	Φ_w	l/min		3.1		5.2		7.8
	Water cooling pressure drop		ΔP_w	bar		1.0		1.5		2.5
	Temperature sensor						PTC 1kΩ / KTY 83-122			
Mechanical	**Coil unit mass**	ex. cables	m	kg		7.3		12.3		18.2
	Coil unit length	ex. cables	L	mm		344		580		852
	Motor attraction force	rms @ 0 A	F_a	N		6300		10700		16050
	Magnet pitch NN		τ	mm			24			
	Cable mass	all cables		kg/m		0.3			0.6	
	Cable type (power)	length 1 m	d	mm (AWG)		11.4 (14)		15.8 (10)		
	Cable type (sensor)	length 1 m	d	mm (AWG)			4.7 (26)			

All specifications ±10%

[1] *These values are only applicable when the mounting surface is at 20°C and the motor is driven at continuous current. If these values differ in your application, please check our simulation tool.*

[2] *Actual values depend on bus voltage. Please check the F/v diagram in our simulation tool.*

Water cooling

All TBW motors feature integrated cooling channels that allow for the easy setup of a liquid cooled system, at no additional cost.

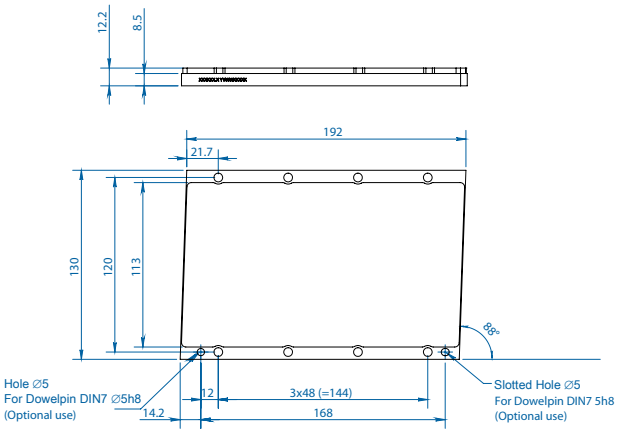
Magnet plate dimensions		
Le (mm)	192	288
M5 bolts	8	12
Mass (kg/m)	10.8	
Magnet plates can be butted together.		

Approvals

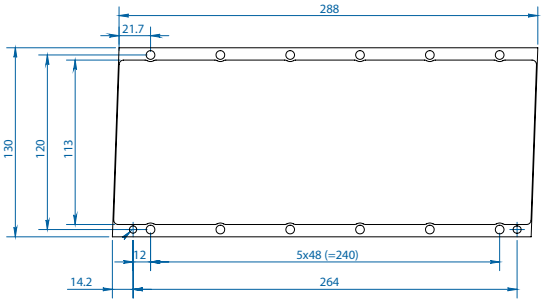
** Expected in 2025.*

Magnet plates

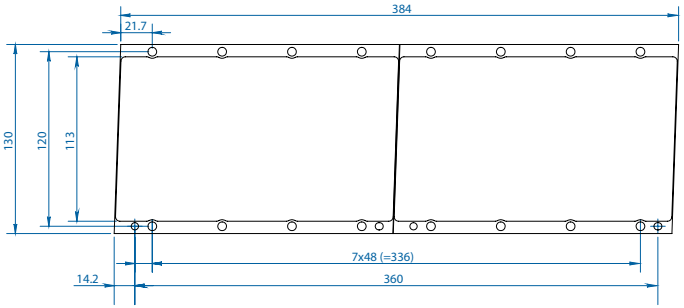
TBX 192 mm



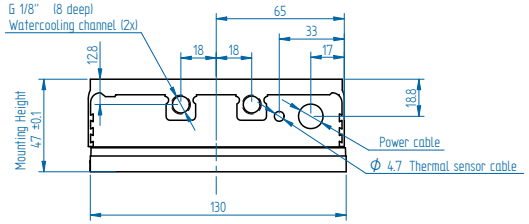
TBX 288 mm



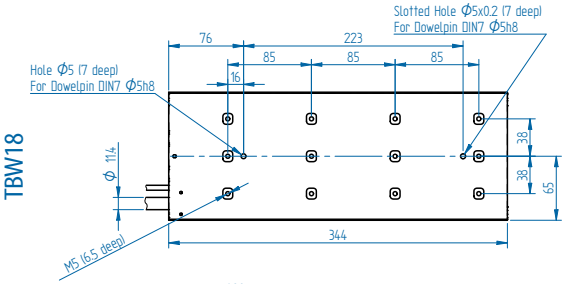
2x TBX 192 mm



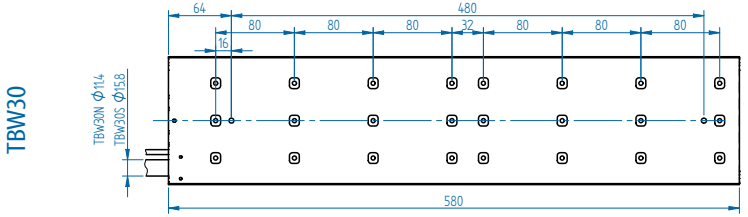
Coil units



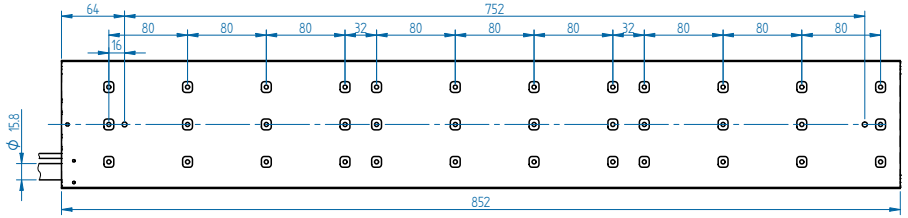
TBW18



TBW30



TBW45



Mounting instructions and flatness or parallelism can be found in the iron core installation manual, and are not different from the standard magnet plate. CAD files, 3D models and the manual can be downloaded from our website.

** All sizes are in mm*

TD55 series

TD55-3 on TD55-192 mm magnet plate

	Parameter	Remarks	Symbol	Unit	TD55-3	TD55-6
Performance	Winding type				N	N
	Motor type, max voltage ph-ph	3-phase synchronous	U_{max}	$V_{ac,rms}$ (V_{dc})	480 (680)	
	Ultimate force @ 10 K/s increase	magnets @ 25°C	F_u	N	211	422
	Peak force @ 6 K/s increase	magnets @ 25°C	F_p	N	161	323
	Continuous force[1]	coils @ 105°C	F_c	N	106	213
	Maximum speed[2]	@ U_{max} @ F_c	v_{max}	m/s	19.8	9.6
	Motor force constant	$I \leq I_c$	K_f	N/A_{rms}	34.4	68.8
	Motor constant	coils @ 25°C	S	N^2/W	140	280
Electrical	Ultimate current	magnets @ 25°C	I_u	A_{rms}	6.9	6.9
	Peak current	magnets @ 25°C	I_p	A_{rms}	5.0	5.0
	Continuous current[1]	coils @ 100°C	I_c	A_{rms}	3.1	3.1
	Back EMF ph-ph $_{peak}$		K_e	V_{dc}/m/s	28.1	56.1
	Resistance per phase	coils @ 25°C ex. cable	R_{ph}	Ω	2.8	5.6
	Induction per phase	$I < 0.6\ I_p$	L_{ph}	mH	13.7	27.4
	Electrical time constant		τ_e	ms	4.9	
Thermal	Continuous power loss[1]	coils @ 105°C	P_c	W	107	213
	Thermal resistance	coils to mount. sfc.	R_{th}	K/W	0.75	0.37
	Thermal time constant		τ_{th}	s	42	
	Temperature sensor				Pt1000 / PTC 1kΩ (2x)	
Mechanical	Coil unit mass	ex. cables	m	kg	0.53	0.89
	Coil unit length	ex. cables	L	mm	95	159
	Motor attraction force	rms @ 0 A	F_a	N	384	768
	Magnet pitch NN		τ	mm	32	
	Cable mass	all cables		kg/m	0.3	
	Cable type	length 1 m	d	mm (AWG)	11 (19)	

All specifications ±10%

[1] *These values are only applicable when the mounting surface is at 20°C and the motor is driven at continuous current. If these values differ in your application, please check our simulation tool.*

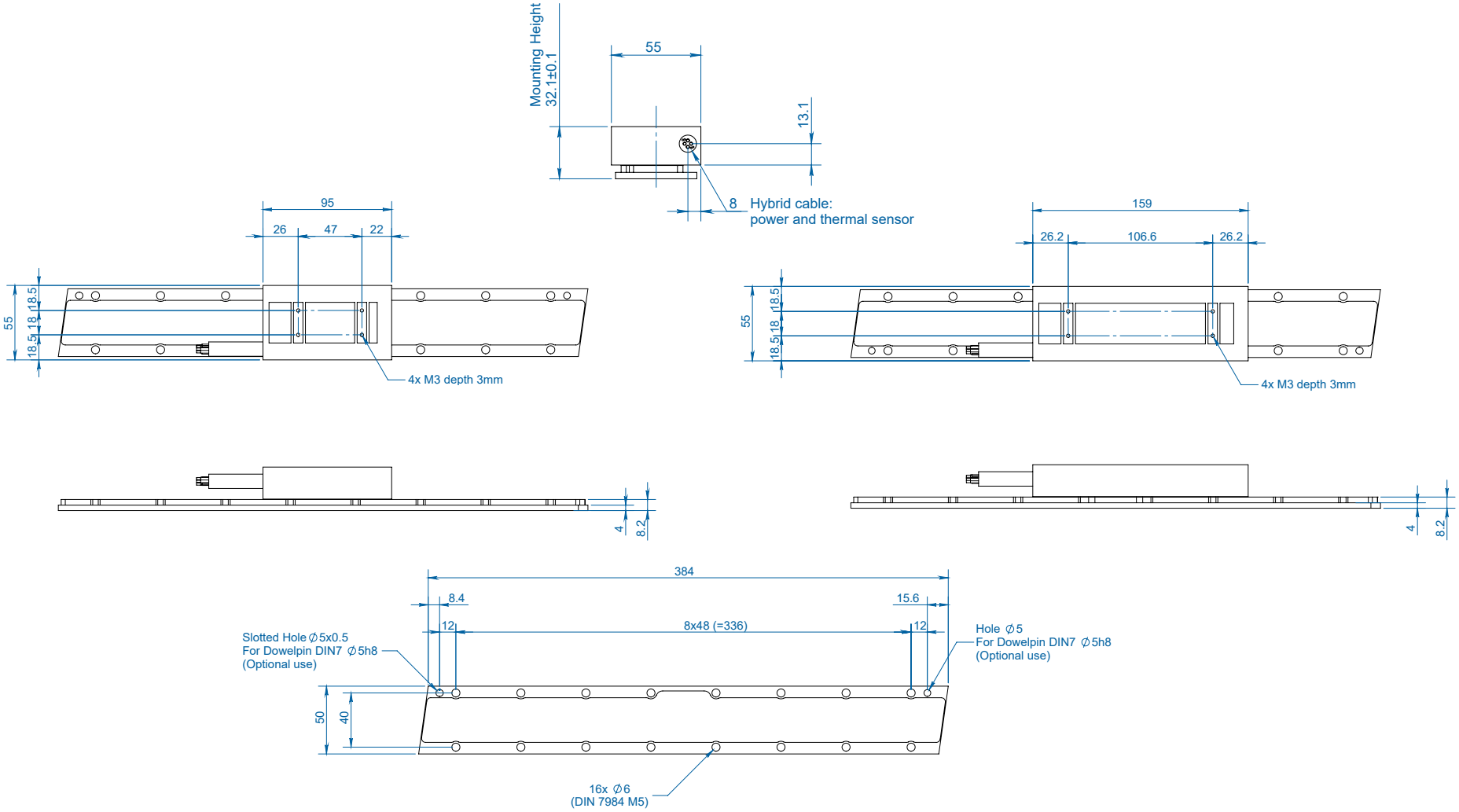
[2] *Actual values depend on bus voltage. Please check the F/v diagram in our simulation tool.*

Magnet plate dimensions		
Le (mm)	96	384
M5 bolts	4	10
Mass (kg/m)[3]	2.24	
Magnet plates can be butted together.		

[3] *Low weight magnet plate available*

TD55-3 &TD55-384 mm

TD55-6 &TD55-384 mm



Mounting instructions and flatness or parallelism requirements can be found in the iron core installation manual. CAD files, 3D models and the manual can be downloaded from our website.

** All sizes are in mm*

TD82-3 on TD82-128 mm magnet plate

TD82 series

	Parameter	Remarks	Symbol	Unit	TD82-3	TD82-6
Performance	Winding type				N	N
	Motor type, max voltage ph-ph	3-phase synchronous	U_{max}	$V_{ac,rms}$ (V_{dc})	480 (680)	
	Ultimate force @ 10 K/s increase	magnets @ 25°C	F_u	N	453	905
	Peak force @ 6 K/s increase	magnets @ 25°C	F_p	N	403	805
	Continuous force[1]	coils @ 105°C	F_c	N	256	524
	Maximum speed[2]	@ U_{max} @ F_c	v_{max}	m/s	262	6.4
	Motor force constant	$I \leq I_c$	K_f	N/A_{rms}	93.6	
	Motor constant	coils @ 25°C	S	N^2/W	498	996
Electrical	Ultimate current	magnets @ 25°C	I_u	A_{rms}	6.5	13.1
	Peak current	magnets @ 25°C	I_p	A_{rms}	5.0	10.0
	Continuous current[1]	coils @ 100°C	I_{cw}	A_{rms}	2.8	5.6
	Back EMF ph-ph $_{peak}$		K_e	V_{dc}/m/s	76.5	76.5
	Resistance per phase	coils @ 25°C ex. cable	R_{ph}	Ω	5.9	2.9
	Induction per phase	$I < 0.6\ I_p$	L_{ph}	mH	54.6	27.3
	Electrical time constant		τ_e	ms	9.3	
Thermal	Continuous power loss[1]	coils @ 105°C	P_c	W	182	364
	Thermal resistance	coils to mount. sfc.	R_{th}	K/W	0.44	0.22
	Thermal time constant		τ_{th}	s	36	
	Temperature sensor				Pt1000 / PTC 1kΩ (2x)	
Mechanical	Coil unit mass	ex. cables	m	kg	1.20	2.13
	Coil unit length	ex. cables	L	mm	95	159
	Motor attraction force	rms @ 0 A	F_a	N	704	1408
	Magnet pitch NN		τ	mm	32	
	Cable mass	all cables		kg/m	0.3	
	Cable type	length 1 m	d	mm (AWG)	11 (19)	

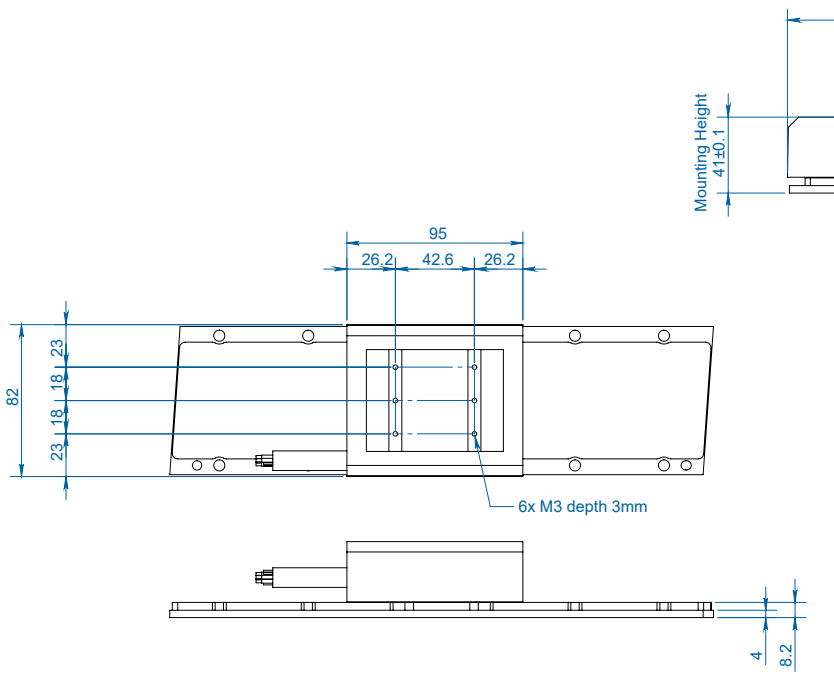
All specifications ±10%

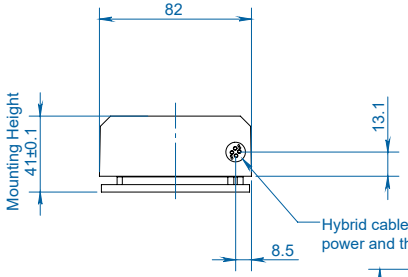
[1] *These values are only applicable when the mounting surface is at 20°C and the motor is driven at continuous current. If these values differ in your application, please check our simulation tool.*

[2] *Actual values depend on bus voltage. Please check the F/v diagram in our simulation tool.*

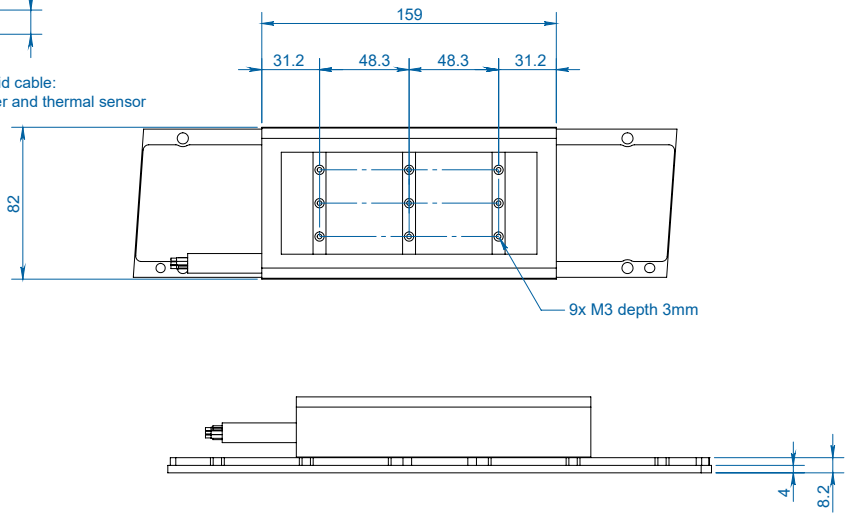
Magnet plate dimensions		
Le (mm)	192	288
M5 bolts	8	12
Mass (kg/m)	3.73	
Magnet plates can be butted together.		

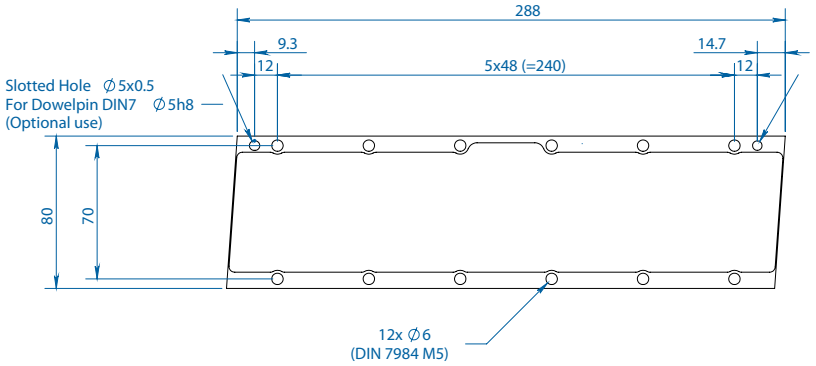
TD82-3 &TD82-288 mm





TD82-6 &TD82-288 mm

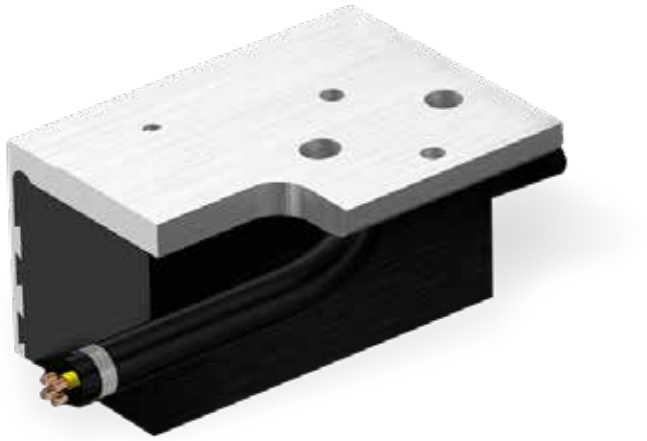


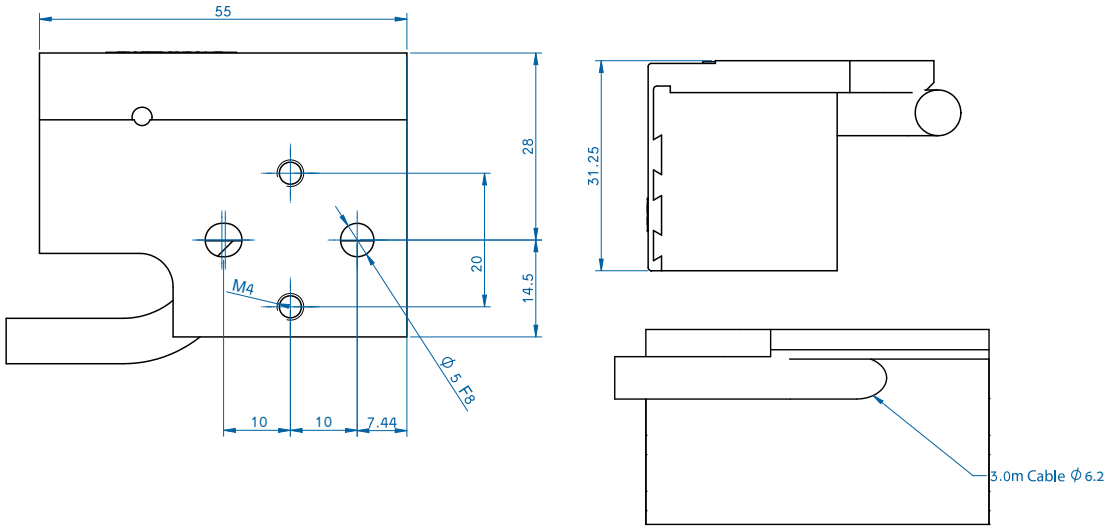


Mounting instructions and flatness or parallelism requirements can be found in the iron core installation manual. CAD files, 3D models and the manual can be downloaded from our website.

** All sizes are in mm*

Analog Hall module



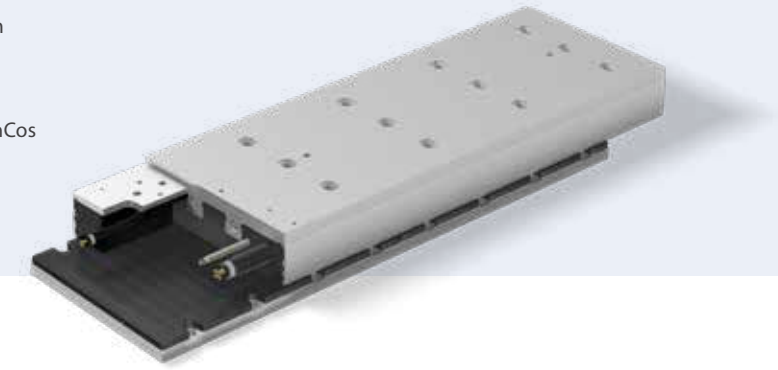


Cost efficient positioning

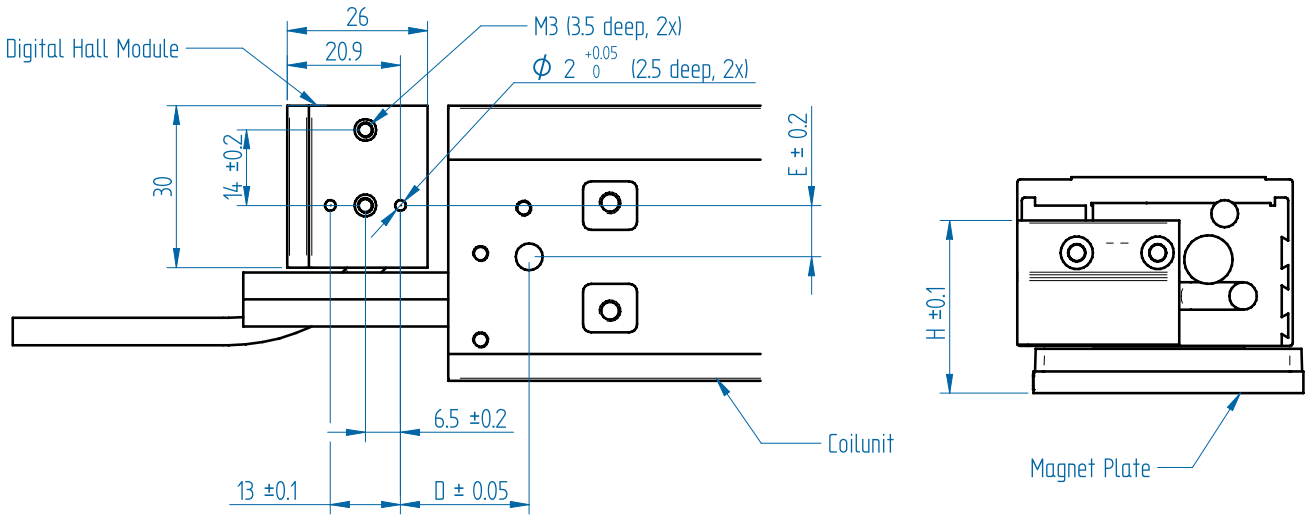
Linear motors can be positioned extremely accurately by using optical encoders and rulers. If extreme accuracy is not required, the optical encoders can be replaced by an analog Hall module. This module uses the magnet track, as opposed to the ruler, as the linear scale.

The analog Hall module can be easily mounted on our iron core motors and communicates with practically all standard servo controllers. The analog Hall module requires a standard $5V_{dc}$ power supply.

Absolute accuracy	± 100 µm
Repeatable accuracy	± 30 µm
Resolution	± 10 µm
Signal	1 Vpp SinCos
Signal period	24 mm



Digital Hall module



Commutation

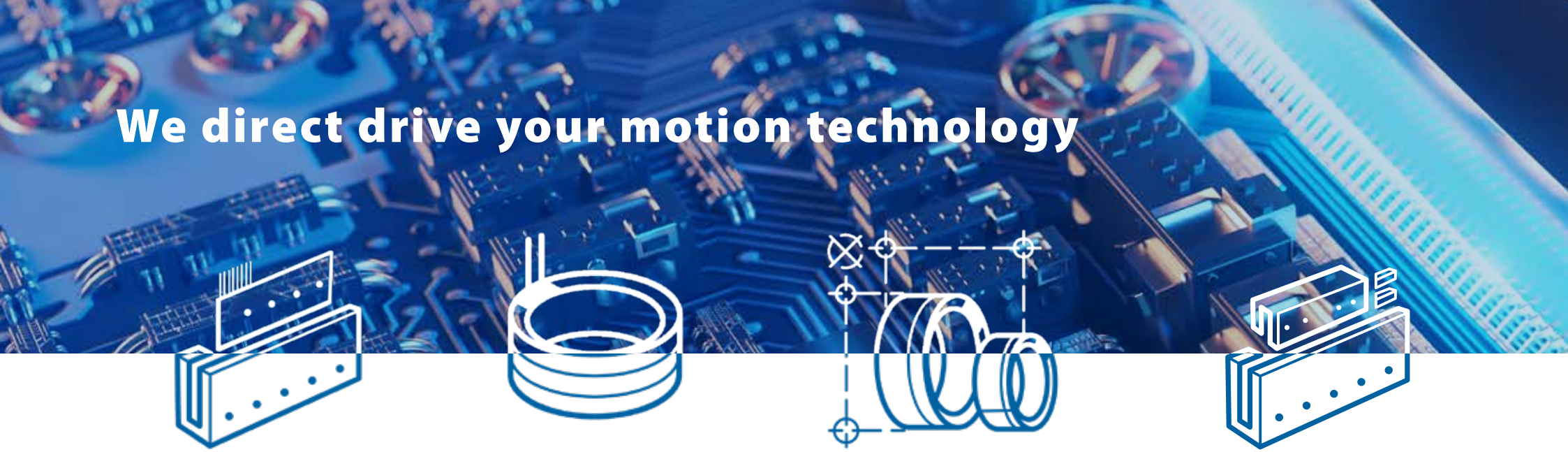
An optional digital Hall module that can be used with our entire range of linear motors, is available for commutation. It's sensors provide 3 digital outputs, each phase shifted 120 degrees, to determine the electrical angle between coils and magnets.

This module can be a cost-effective alternative, if you don't use a controller that allows you to commutate within the servo drive.

- The digital Hall module requires a 4 to 24V_{dc} power supply.

Mounting instructions and flatness or parallelism requirements can be found in the iron core installation manual. CAD files and 3D models can be downloaded from our website.

We direct drive your motion technology



Vacuum linear motors

F_p 100-4020 N F_c 22-698 N

Vacuum Generation 2 motors for powerful and precise processes

Generation 2 vacuum ironless linear motor series is designed with the unique challenges of vacuum applications in mind and based on years of collaboration with high-end semiconductor manufacturers.

Optimal thermal properties, added safety, excellent RGA performance, lower outgassing and flexibility to install make the Generation 2 vacuum motor series the benchmark for motion in vacuum applications.

www.tecnotion.com/vacuum

Torque motors

T_u 0.64-2202 Nm T_c 0.29-907 Nm

Increased accuracy and dynamic performance of your application

Tecnotion torque motor series features superior torque density, low thermal resistance, low cogging and housed design. Motors can be very slim in height but large in diameter (for large axles and turntables) or have a 'height' close to their diameter, resulting in a compact but high-torque motor.

The torque series consists of different outer diameters ranging from 65mm to 485mm for the largest motor and various building heights ranging from 17mm up to 138mm.

www.tecnotion.com/torque

Custom motors

Motor solutions

Adapt standard motor series to meet your needs

In case the standard motor series are not sufficient for your application, it is also possible to have these motors customized in a variety of ways. Customization can range from simple modifications, like adding a connector, to fully tailor-made motors designed from scratch.

Some examples: custom windings, cable confection, additional sensors, additional certifications and customization for vacuum applications. For more information please contact Tecnotion.

www.tecnotion.com/custom

Ironless linear motors

F_p 36-4200 N F_c 10-846 N

Superior precision with accurate force constant and speed

In contrast to iron core motors, these motors feature an ironless coil unit, therefore no attraction force or cogging between the coil unit and the magnet track. This gives ironless motors their light weight, superior precision, a linear force constant, and extremely dynamic velocity, acceleration, and deceleration.

Perfect for many industries, such as semiconductor, display, inspection, medical, automation, and optics.

www.tecnotion.com/ironless

TECNOTION® direct drive in motion

Motor simulation tool

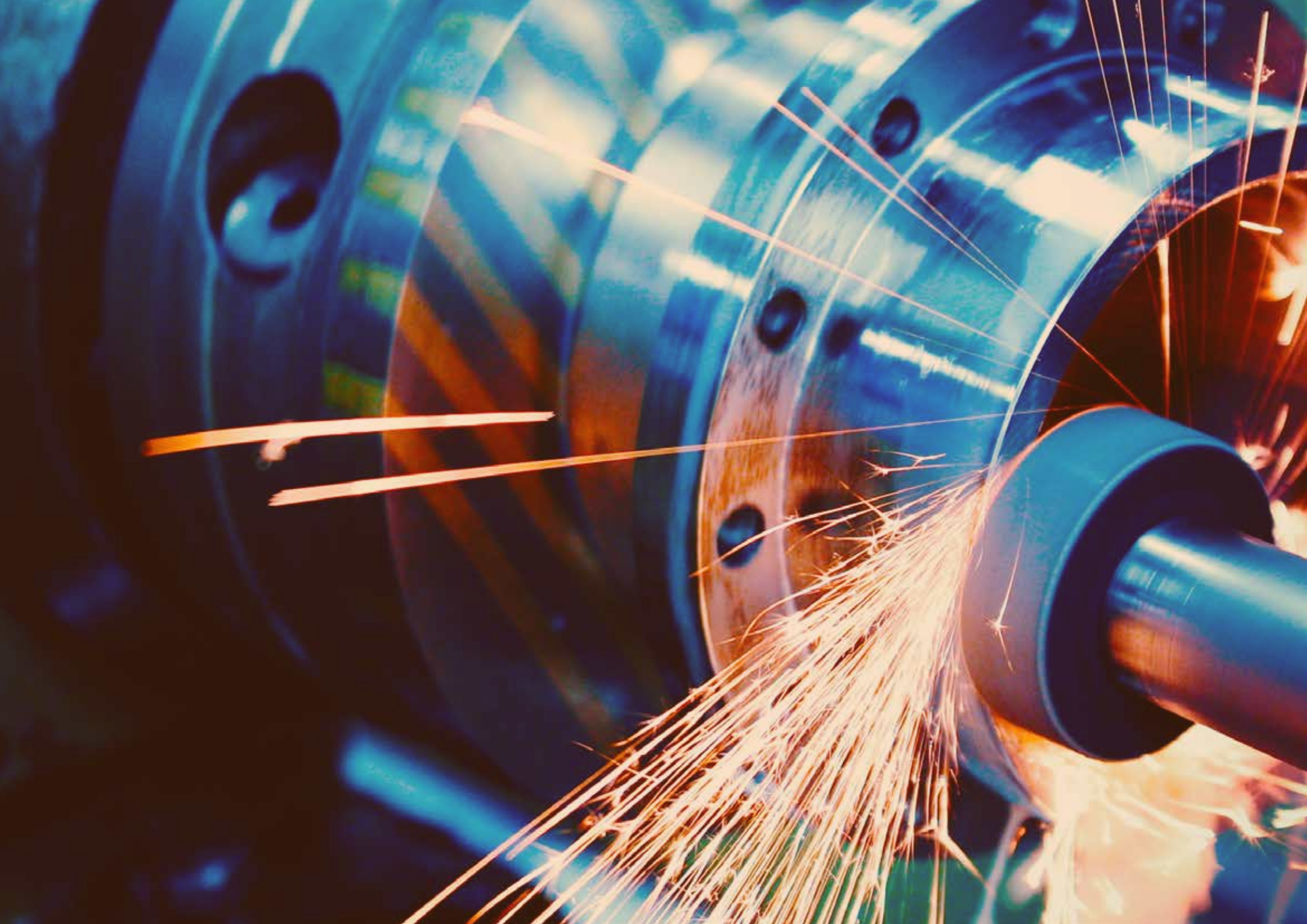
Analyze your application

Size your application with the motor selection and simulation tool

Online motor simulation software helps you find the best motor for the application and generate reports within seconds, without having to make time consuming calculations by hand.

The motor sizing simulation tool helps to select the right torque motor or linear motor, using your application characteristics. The tool will provide you with diagrams for position, velocity, acceleration, jerk, force, power, voltage, current, temperature and force vs. velocity.

www.tecnotion.com/simtool



Article numbers

Series	Article	Article code
Modules		
All series	Analog Hall Module	4022 368 5139
All series	Digital Hall Module T-Serie	4022 368 5418
TM series		
TM	Coil unit TM 3S FLEX	4022 368 5075
TM	Coil unit TM 3Z FLEX	4022 368 5533
TM	Coil unit TM 6S FLEX	4022 368 5076
TM	Coil unit TM 6Z FLEX	4022 368 5300
TM	Coil unit TM 12S FLEX	4022 368 5078
TM	Coil unit TM 18N FLEX	4022 368 5500
TM	Coil unit TM 18S FLEX	4022 368 5519
TM	Magnet plate TM 96 mm	4022 368 5225
TM	Magnet plate TM 144 mm	4022 368 5226
TM	Magnet plate TM 384 mm	4022 368 5227
TMX series		
TMX	Magnet plate TMX 96mm	118239
TMX	Magnet plate TMX 144mm	118244
TMX	Magnet plate TMX 384mm	118248
TL series		
TL	Coil unit TL 6N	4022 369 7458
TL	Coil unit TL 6S	4022 368 5032
TL	Coil unit TL 9N	4022 368 5311
TL	Coil unit TL 9S	4022 368 5312
TL	Coil unit TL 12N	4022 369 7459
TL	Coil unit TL 12S	4022 368 5033
TL	Coil unit TL 15N	4022 369 7460
TL	Coil unit TL 15S	4022 368 5034

Series	Article	Article code
TL	Coil unit TL 18N	4022 368 5223
TL	Coil unit TL 18S	4022 368 5224
TL	Coil unit TL 24N	4022 368 5014
TL	Coil unit TL 24S	4022 368 5035
TL	Coil unit TL 48Q	112547
TL	Magnet plate TL 192 mm	4022 368 5193
TL	Magnet plate TL 288 mm	4022 368 5194
TLX series		
TLX	Magnet plate TLX 192mm	118252
TLX	Magnet plate TLX 288 mm	117485
TB series		
TB	Coil unit TB 12N	4022 368 5155
TB	Coil unit TB 12S	4022 368 5157
TB	Coil unit TB 15N	4022 368 5122
TB	Coil unit TB 15S	4022 368 5120
TB	Coil unit TB 18N	111026
TB	Coil unit TB 24N	111027
TB	Coil unit TB 30N	4022 368 5123
TB	Coil unit TB 30S	4022 368 5121
TB	Magnet plate TB 192 mm	4022 368 5221
TB	Magnet plate TB 288 mm	4022 368 5222
TBX series		
TBX	Magnet plate TBX 192 mm	118256
TBX	Magnet plate TBX 288 mm	118260
TBW series		
TBW	Coil unit TBW 18N	4022 368 5263
TBW	Coil unit TBW 18S	4022 368 5264

Series	Article	Article code
TBW	Coil unit TBW 30N	4022 368 5242
TBW	Coil unit TBW 30S	4022 368 5243
TBW	Coil unit TBW 45N	4022 368 5244
TBW	Coil unit TBW 45S	4022 368 5245
TBW	Magnet plate TB 192 mm	4022 368 5221
TBW	Magnet plate TB 288 mm	4022 368 5222
TBWX series		
TBX	Magnet plate TBX 192 mm	118256
TBX	Magnet plate TBX 288 mm	118260
TD series		
TD55	Coil unit TD55-3N	121239
TD55	Coil unit TD55-6N	121240
TD55	Magnet plate TD55 96mm	121243
TD55	Magnet plate TD55 384mm	121244
TD82	Coil unit TD82-3N	121241
TD82	Coil unit TD82-6N	121242
TD82	Magnet plate TD82 192mm	121245
TD82	Magnet plate TD82 288mm	121246

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